## Course: Calculus (3)

## Chapter: [12] <br> VECTOR-VALUED FUNCTIONS

Section: [12.1]
INTRODUCTION TO VECTOR-VALUED FUNCTIONS

## IN THIS CHAPTER

$\checkmark$ We will consider functions whose values are vectors.

> Functions that associate vectors with real numbers.
$\checkmark$ In this section we will discuss more general parametric curves, and we will show how vector notation can be used to express parametric equations in a more compact form.

## VECTOR-VALUED FUNCTIONS

A function of the form

$$
\begin{aligned}
\mathbf{r}(t) & =f(t) \mathbf{i}+g(t) \mathbf{j}+h(t) \mathbf{k} \\
& =\langle f(t), g(t), h(t)\rangle
\end{aligned}
$$

is a vector-valued function, where the component functions $f, g$ and $h$ are real-valued functions of the parameter $t$.



## PARAMETRIC CURVES IN 3 -SPACE

Example The parametric equations

$$
\begin{aligned}
& x=1-t \\
& y=3 t \\
& z=2 t
\end{aligned}
$$

represent a line in 3 -space that passes through the point $(1,0,0)$ and is parallel to the vector $\langle-1,3,2\rangle$.

$$
\begin{aligned}
\mathbf{r}(t) & =(1-t) \mathbf{i}+3 t \mathbf{j}+2 t \mathbf{k} \\
& =\langle 1-t, 3 t, 2 t\rangle
\end{aligned}
$$

## PARAMETRIC CURVES IN 3 -SPACE

Example Describe the parametric curve represented by the equations


$$
\begin{aligned}
& x=10 \cos t \\
& y=10 \sin t \\
& z=t \\
& \\
& \begin{aligned}
\mathbf{r}(t) & =10 \cos t \mathbf{i}+10 \sin t \mathbf{j}+t \mathbf{k} \\
& =\langle 10 \cos t, 10 \sin t, t\rangle
\end{aligned}
\end{aligned}
$$



Circular HELIX

## VECTOR-VALUED FUNCTIONS

The domain of a vector-valued function $\mathbf{r}(t)$ is the set of allowable values for $t$.

NOTE Usual reasons to restrict a domain:

1. Avoid division by 0 .
2. Avoid even roots of negative numbers.
3. Avoid logarithms of negative numbers or 0 .

## VECTOR-VALUED FUNCTIONS

Example Find the natural domain of $\quad \mathbf{r}(t)=\ln |t-1| \mathbf{i}+e^{t} \mathbf{j}+\sqrt{t} \mathbf{k}$

$$
\begin{array}{ll}
x(t)=\ln |t-1| & \square \text { Domain }=\mathbb{R}-\{1\} \\
y(t)=e^{t} & \square \text { Domain }=\mathbb{R} \\
z(t)=\sqrt{t} & \square \text { Domain }=[0, \infty)
\end{array}
$$

$\therefore$ The domain of $\mathbf{r}(t)$ is the intersection of these sets.

## Course: Calculus (3)

Chapter: [12]<br>VECTOR-VALUED FUNCTIONS

Section: [12.2]
CALCULUS OF VECTOR-VALUED FUNCTIONS

## LIMITS AND CONTINUITY

- Many techniques and definitions used in the calculus of realvalued functions can be applied to vector-valued functions.
- For instance, you can add and subtract vector-valued functions, multiply a vector-valued function by a scalar, take the limit of a vector-valued function, differentiate a vectorvalued function, and so on.


## LIMITS AND CONTINUITY

$$
\begin{aligned}
\mathbf{r}_{1}(t)+\mathbf{r}_{2}(t) & =\left[f_{1}(t) \mathbf{i}+g_{1}(t) \mathbf{j}\right]+\left[f_{2}(t) \mathbf{i}+g_{2}(t) \mathbf{j}\right] \\
& =\left[f_{1}(t)+f_{2}(t)\right] \mathbf{i}+\left[g_{1}(t)+g_{2}(t)\right] \mathbf{j} . \\
\mathbf{r}_{1}(t)-\mathbf{r}_{2}(t) & =\left[f_{1}(t) \mathbf{i}+g_{1}(t) \mathbf{j}\right]-\left[f_{2}(t) \mathbf{i}+g_{2}(t) \mathbf{j}\right] \\
& =\left[f_{1}(t)-f_{2}(t)\right] \mathbf{i}+\left[g_{1}(t)-g_{2}(t)\right] \mathbf{j} .
\end{aligned}
$$

$$
\begin{aligned}
c \mathbf{r}(t) & =c\left[f_{1}(t) \mathbf{i}+g_{1}(t) \mathbf{j}\right] \\
& =c f_{1}(t) \mathbf{i}+c g_{1}(t) \mathbf{j} .
\end{aligned}
$$

$$
\begin{aligned}
\frac{\mathbf{r}(t)}{c} & =\frac{\left[f_{1}(t) \mathbf{i}+g_{1}(t) \mathbf{j}\right]}{c}, \quad c \neq 0 \\
& =\frac{f_{1}(t)}{c} \mathbf{i}+\frac{g_{1}(t)}{c} \mathbf{j} .
\end{aligned}
$$

## LIMITS AND CONTINUITY

If $\mathbf{r}$ is a vector-valued function such that $\mathbf{r}(t)=f(t) \mathbf{i}+g(t) \mathbf{j}+h(t) \mathbf{k}$, then

$$
\lim _{t \rightarrow a} \mathbf{r}(t)=\left[\lim _{t \rightarrow a} f(t)\right] \mathbf{i}+\left[\lim _{t \rightarrow a} g(t)\right] \mathbf{j}+\left[\lim _{t \rightarrow a} h(t)\right] \mathbf{k}
$$

provided $f, g$, and $h$ have limits as $t \rightarrow a$.
Example If $\mathbf{r}(t)=\frac{3}{t^{2}} \mathbf{i}+\frac{\ln t}{t^{2}-1} \mathbf{j}+\cos (\pi t) \mathbf{k}$, find $\lim _{t \rightarrow 1} \mathbf{r}(t)$.

$$
\begin{aligned}
\lim _{t \rightarrow 1} \mathbf{r}(t) & =\left\langle 3, \frac{1}{2},-1\right\rangle \\
& =3 \mathbf{i}+\frac{1}{2} \mathbf{j}-\mathbf{k}
\end{aligned}
$$

$$
\lim _{t \rightarrow 1} \frac{3}{t^{2}}=3
$$

$$
\lim _{t \rightarrow 1} \frac{\ln t}{t^{2}-1}=\lim _{t \rightarrow 1} \frac{1 / t}{2 t}=\frac{1}{2}
$$

$$
\lim _{t \rightarrow 1} \cos (\pi t)=-1
$$

## LIMITS AND CONTINUITY

Example If $\mathbf{r}(t)=\frac{2 t^{2}-1}{t^{2}+t} \mathbf{i}+\sin \left(\frac{1}{t}\right) \mathbf{j}+t e^{-t} \mathbf{k}$, find $\lim _{t \rightarrow \infty} \mathbf{r}(t)$.

$$
\lim _{t \rightarrow \infty} \mathbf{r}(t)=\langle 2,0,0\rangle=2 \mathbf{i}
$$

$$
\begin{aligned}
& \lim _{t \rightarrow \infty} \frac{2 t^{2}-1}{t^{2}+t}=2 \\
& \lim _{t \rightarrow \infty} \sin \left(\frac{1}{t}\right)=0
\end{aligned}
$$

$$
\begin{aligned}
\lim _{t \rightarrow \infty} t e^{-t} & =0 \cdot \infty \\
& =\lim _{t \rightarrow \infty} \frac{t}{e^{t}}=\lim _{t \rightarrow \infty} \frac{1}{e^{t}}=0
\end{aligned}
$$

## LIMITS AND CONTINUITY

A vector-valued function $\mathbf{r}$ is continuous at the point given by $t=a$ when the limit of $\mathbf{r}(t)$ exists as $t \rightarrow a$ and

$$
\lim _{t \rightarrow a} \mathbf{r}(t)=\mathbf{r}(a)
$$

A vector-valued function $\mathbf{r}$ is continuous on an interval $I$ when it is continuous at every point in the interval.

Example The vector-valued function $\mathbf{r}(t)=t^{2} \mathbf{i}+\frac{1}{t^{2}-1} \mathbf{j}+t \mathbf{k}$, is discontinuous at $t= \pm 1$.

It is continuous for all $t \in \mathbb{R}-\{-1,1\}$

## DERIVATIVES

- The derivative of a vector-valued function is defined by a limit like that for the derivative of a real-valued function.

$$
\mathbf{r}^{\prime}(t)=\lim _{h \rightarrow 0} \frac{\mathbf{r}(t+h)-\mathbf{r}(t)}{h}
$$

- The derivative of $\mathbf{r}(t)$ can be expressed as

$$
\frac{d}{d t}[\mathbf{r}(t)], \quad \frac{d \mathbf{r}}{d t}, \quad \mathbf{r}^{\prime}(t), \quad \mathbf{r}^{\prime}
$$

- Keep in mind that $\mathbf{r}(t)$ is a vector, not a number, and hence has a magnitude and a direction for each value of $t$, except if $\mathbf{r}(t)=\mathbf{0}$.


## DERIVATIVES

Suppose that $C$ is the graph of a vector-valued function $\mathbf{r}(t)$ and that $\mathbf{r}^{\prime}(t)$ exists and is nonzero for a given value of $t$.

If the vector $\mathbf{r}^{\prime}(t)$ is positioned with its initial point at the terminal point of the radius vector $\mathbf{r}(t)$, then $\mathbf{r}^{\prime}(t)$ is tangent to $C$ and points in the direction of increasing parameter.


## DERIVATIVES

If $\mathbf{r}(t)=f(t) \mathbf{i}+g(t) \mathbf{j}+h(t) \mathbf{k}$, where $f, g$, and $h$ are differentiable functions of $t$, then

$$
\mathbf{r}^{\prime}(t)=f^{\prime}(t) \mathbf{i}+g^{\prime}(t) \mathbf{j}+h^{\prime}(t) \mathbf{k} .
$$

Example For the vector-valued function

$$
\mathbf{r}(t)=t \mathbf{i}+\left(t^{2}+2\right) \mathbf{j}, \text { find } \mathbf{r}^{\prime}(1) .
$$

$$
\mathbf{r}^{\prime}(t)=\mathbf{i}+2 t \mathbf{j}
$$

$$
\mathbf{r}^{\prime}(1)=\mathbf{i}+2 \mathbf{j}
$$



## DERIVATIVES

Example For the vector-valued function $\mathbf{r}(t)=\cos t \mathbf{i}+\sin t \mathbf{j}+2 t \mathbf{k}$, find:
(1) $\mathbf{r}^{\prime}(t)$ $\mathbf{r}^{\prime}(t)=-\sin t \mathbf{i}+\cos t \mathbf{j}+2 \mathbf{k}$
(2) $\mathbf{r}^{\prime \prime}(t)$ $\mathbf{r}^{\prime \prime}(t)=-\cos t \mathbf{i}-\sin t \mathbf{j}$
(3) $\mathbf{r}^{\prime}(t) \cdot \mathbf{r}^{\prime \prime}(t) \quad \mathbf{r}^{\prime}(t) \cdot \mathbf{r}^{\prime \prime}(t)=\sin t \cos t-\cos t \sin t=0$
(4) $\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)$
$\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)=\left|\begin{array}{ccc}\mathbf{i} & \mathbf{j} & \mathbf{k} \\ -\sin t & \cos t & 2 \\ -\cos t & -\sin t & 0\end{array}\right|=2 \sin t \mathbf{i}-2 \cos t \mathbf{j}+\mathbf{k}$

1. $\frac{d}{d t}[c \mathbf{r}(t)]=c \mathbf{r}^{\prime}(t)$
2. $\frac{d}{d t}[\mathbf{r}(t) \pm \mathbf{u}(t)]=\mathbf{r}^{\prime}(t) \pm \mathbf{u}^{\prime}(t)$
3. $\frac{d}{d t}[w(t) \mathbf{r}(t)]=w(t) \mathbf{r}^{\prime}(t)+w^{\prime}(t) \mathbf{r}(t)$
4. $\frac{d}{d t}[\mathbf{r}(t) \cdot \mathbf{u}(t)]=\mathbf{r}(t) \cdot \mathbf{u}^{\prime}(t)+\mathbf{r}^{\prime}(t) \cdot \mathbf{u}(t)$
5. $\frac{d}{d t}[\mathbf{r}(t) \times \mathbf{u}(t)]=\mathbf{r}(t) \times \mathbf{u}^{\prime}(t)+\mathbf{r}^{\prime}(t) \times \mathbf{u}(t)$
6. $\frac{d}{d t}[\mathbf{r}(w(t))]=\mathbf{r}^{\prime}(w(t)) w^{\prime}(t)$
7. If $\mathbf{r}(t) \cdot \mathbf{r}(t)=c$, then $\mathbf{r}(t) \cdot \mathbf{r}^{\prime}(t)=0$.

## DERIVATIVE RULES

Example For $\mathbf{u}(t)=\frac{1}{t} \mathbf{i}-\mathbf{j}+\ln t \mathbf{k}$ and $\mathbf{v}(t)=t^{2} \mathbf{i}-2 t \mathbf{j}+\mathbf{k}$ then:
(1) $\frac{d}{d t}[\mathbf{u}(t) \cdot \mathbf{v}(t)]=\mathbf{u}(t) \cdot \mathbf{v}^{\prime}(t)+\mathbf{u}^{\prime}(t) \cdot \mathbf{v}(t)$

$$
=\left\langle\frac{1}{t},-1, \ln t\right\rangle \cdot\langle 2 t,-2,0\rangle+\left\langle\frac{-1}{t^{2}}, 0, \frac{1}{t}\right\rangle \cdot\left\langle t^{2},-2 t, 1\right\rangle
$$

$$
=(2+2+0)+\left(-1+0+\frac{1}{t}\right)
$$

$$
=3+\frac{1}{t}
$$

## DERIVATIVE RULES

Example For $\mathbf{u}(t)=\frac{1}{t} \mathbf{i}-\mathbf{j}+\ln t \mathbf{k}$ and $\mathbf{v}(t)=t^{2} \mathbf{i}-2 t \mathbf{j}+\mathbf{k}$ then:
(2) $\frac{d}{d t}\left[\mathbf{v}(t) \times \mathbf{v}^{\prime}(t)\right]=\mathbf{v}(t) \times \mathbf{v}^{\prime \prime}(t)+\mathbf{v}^{\prime}(t) \times \mathbf{v}^{\prime}(t)$

$$
\begin{aligned}
& =\left|\begin{array}{ccc}
\mathbf{i} & \mathbf{j} & \mathbf{k} \\
t^{2} & -2 t & 1 \\
2 & 0 & 0
\end{array}\right|+\mathbf{0} \\
& =2 \mathbf{j}+4 t \mathbf{k}
\end{aligned}
$$

## TANGENT LINES TO GRAPHS OF VECTOR-VALUED FUNCTIONS

Example Find parametric equations of the tangent line to the circular helix $\mathbf{r}(t)=\cos t \mathbf{i}+\sin t \mathbf{j}+t \mathbf{k}$ at the point where $t=\pi$.

$$
t=\pi
$$

## POINT

$$
(\cos \pi, \sin \pi, \pi)=(-1,0, \pi)
$$

TANGENT VECTOR
$\mathbf{r}^{\prime}(t)=-\sin t \mathbf{i}+\cos t \mathbf{j}+\mathbf{k}$
$\mathbf{r}^{\prime}(\pi)=-\mathbf{j}+\mathbf{k}$
$\therefore$ The parametric equations of the tangent line are

$$
\begin{aligned}
& x=-1 \\
& y=-t \\
& z=\pi+t
\end{aligned}
$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

In general, we have

$$
\int_{a}^{b} \mathbf{r}(t) d t=\left(\int_{a}^{b} x(t) d t\right) \mathbf{i}+\left(\int_{a}^{b} y(t) d t\right) \mathbf{j}+\left(\int_{a}^{b} z(t) d t\right) \mathbf{k}
$$

Example Let $\mathbf{r}(t)=t^{2} \mathbf{i}+e^{t} \mathbf{j}-2 \cos (\pi t) \mathbf{k}$. Then

$$
\begin{aligned}
\int_{0}^{1} \mathbf{r}(t) d t & =\left(\int_{0}^{1} t^{2} d t\right) \mathbf{i}+\left(\int_{0}^{1} e^{t} d t\right) \mathbf{j}-\left(\int_{0}^{1} 2 \cos \pi t d t\right) \mathbf{k} \\
& \left.\left.\left.=\frac{t^{3}}{3}\right]_{0}^{1} \mathbf{i}+e^{t}\right]_{0}^{1} \mathbf{j}-\frac{2}{\pi} \sin \pi t\right]_{0}^{1} \mathbf{k}=\frac{1}{3} \mathbf{i}+(e-1) \mathbf{j}
\end{aligned}
$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

$$
\text { Example } \begin{aligned}
\int\left(2 t \mathbf{i}+3 t^{2} \mathbf{j}\right) d t & =\left(\int 2 t d t\right) \mathbf{i}+\left(\int 3 t^{2} d t\right) \mathbf{j} \\
& =\left(t^{2}+C_{1}\right) \mathbf{i}+\left(t^{3}+C_{2}\right) \mathbf{j} \\
& =\left(t^{2} \mathbf{i}+t^{3} \mathbf{j}\right)+\left(C_{1} \mathbf{i}+C_{2} \mathbf{j}\right)=\left(t^{2} \mathbf{i}+t^{3} \mathbf{j}\right)+\mathbf{C}
\end{aligned}
$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

Example Find $\mathbf{r}(t)$ given that $\mathbf{r}^{\prime}(t)=\langle 3,2 t\rangle$ and $\mathbf{r}(1)=\langle 2,5\rangle$.

$$
\begin{aligned}
\mathbf{r}(t)=\int \mathbf{r}^{\prime}(t) d t=\int\langle 3,2 t\rangle d t=\left\langle 3 t, t^{2}\right\rangle+\mathbf{C} \\
\text { But } \left.\quad \begin{array}{rlrl}
\mathbf{r}(1) & =\langle 2,5\rangle \\
\langle 3,1\rangle+\mathbf{C} & =\langle 2,5\rangle & \text { So } \quad \begin{array}{rl}
\mathbf{r}(t) & =\left\langle 3 t, t^{2}\right\rangle+\langle-1,4\rangle \\
\mathbf{C} & =\langle-1,4\rangle
\end{array} & \mathbf{r}(t)
\end{array}\right)=\left\langle 3 t-1, t^{2}+4\right\rangle
\end{aligned}
$$

## Course: Calculus (3)

## Chapter: [12] <br> VECTOR-VALUED FUNCTIONS

Section: [12.3]
CHANGE OF PARAMETER; ARC LENGTH

## SMOOTH PARAMETRIZATIONS

- We will say that a curve represented by $\mathbf{r}(t)$ is smoothly parametrized by $\mathbf{r}(t)$, or that $\mathbf{r}(t)$ is a smooth function of $t$ if:
$\checkmark \mathbf{r}^{\prime}(t)$ is continuous, and
$\checkmark \mathbf{r}^{\prime}(t) \neq \mathbf{0}$ for any allowable value of $t$.
- Geometrically, this means that a smoothly parametrized curve can have no abrupt (مفاجئ) changes in direction as the parameter increases.


## SMOOTH PARAMETRIZATIONS

Example Determine whether the following vector-valued functions are smooth.
(1) $\mathbf{r}(t)=a \cos t \mathbf{i}+a \sin t \mathbf{j}+c t \mathbf{k} \quad a>0, c>0$
$\mathbf{r}^{\prime}(t)=-a \sin t \mathbf{i}+a \cos t \mathbf{j}+c \mathbf{k}$
$\checkmark$ The components are continuous functions, and
$\checkmark$ there is no value of $t$ for which all three of them are zero.
$\checkmark$ So $\mathbf{r}(t)$ is a smooth function.

## SMOOTH PARAMETRIZATIONS

Example Determine whether the following vector-valued functions are smooth.
(2) $\mathbf{r}(t)=t^{2} \mathbf{i}+t^{3} \mathbf{j}$
$\mathbf{r}^{\prime}(t)=2 t \mathbf{i}+3 t^{2} \mathbf{j}$
$\checkmark$ The components are continuous functions, and
$\checkmark$ they are both equal to zero if $t=0$.
$\checkmark$ So, $\mathbf{r}(t)$ is NOT a smooth function.


## ARC LENGTH FROM THE VECTOR VIEWPOINT

If $C$ is the graph of a smooth vector-valued function $\mathbf{r}(t)$, then its arc length $\ell$ from $t=a$ to $t=b$ is

$$
\ell=\int_{a}^{b}\left\|\frac{d \mathbf{r}}{d t}\right\| d t=\int_{a}^{b} \sqrt{\left(\frac{d x}{d t}\right)^{2}+\left(\frac{d y}{d t}\right)^{2}+\left(\frac{d z}{d t}\right)^{2}} d t
$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t)=$ $\langle\cos t, \sin t, t\rangle$ from $t=0$ to $t=\pi$.

## ARC LENGTH FROM THE VECTOR VIEWPOINT

$$
\ell=\int_{a}^{b}\left\|\frac{d \mathbf{r}}{d t}\right\| d t=\int_{a}^{b} \sqrt{\left(\frac{d x}{d t}\right)^{2}+\left(\frac{d y}{d t}\right)^{2}+\left(\frac{d z}{d t}\right)^{2}} d t
$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t)$

$$
=\langle\cos t, \sin t, t\rangle \text { from } t=0 \text { to } t=\pi .
$$

$$
\begin{aligned}
\mathbf{r}^{\prime}(t) & =\langle-\sin t, \cos t, 1\rangle \\
\left\|\mathbf{r}^{\prime}(t)\right\| & =\sqrt{(-\sin t)^{2}+\cos ^{2} t+1} \\
& =\sqrt{2}
\end{aligned}
$$

$$
\begin{aligned}
\ell & =\int_{0}^{\pi}\left\|\mathbf{r}^{\prime}(t)\right\| d t \\
& =\int_{0}^{\pi} \sqrt{2} d t \\
& =\sqrt{2} \pi
\end{aligned}
$$

## Course: Calculus (3)

## Chapter: [12] <br> VECTOR-VALUED FUNCTIONS

Section: [12.4]
UNIT TANGENT, NORMAL, AND BINORMAL VECTORS

## UNIT TANGENT VECTORS

- Recall that if $C$ is the graph of a smooth vector-valued function $\mathbf{r}(t)$, then the vector $\mathbf{r}^{\prime}(t)$ is:
$\checkmark$ nonzero, tangent to $C$, and
$\checkmark$ points in the direction of increasing parameter.
- Thus, by normalizing $\mathbf{r}^{\prime}(t)$ we obtain a unit vector

that is tangent to $C$ and points in the direction of increasing parameter.
- We call $\mathbf{T}(t)$ the unit tangent vector to $C$ at $t$.


## UNIT TANGENT VECTORS

Example Find the unit tangent vector to the graph of $\mathbf{r}(t)=t^{2} \mathbf{i}+t^{3} \mathbf{j}$ at the point where $t=2$.

$$
\begin{aligned}
\mathbf{r}^{\prime}(t) & =2 t \mathbf{i}+3 t^{2} \mathbf{j} \\
\mathbf{r}^{\prime}(2) & =4 \mathbf{i}+12 \mathbf{j} \\
\mathbf{T}(2) & =\frac{\mathbf{r}^{\prime}(2)}{\left\|\mathbf{r}^{\prime}(2)\right\|} \\
& =\frac{4 \mathbf{i}+12 \mathbf{j}}{\sqrt{160}}=\frac{1}{\sqrt{10}} \mathbf{i}+\frac{3}{\sqrt{10}} \mathbf{j}
\end{aligned}
$$



## UNIT NORMAL VECTORS

- Recall if $\|\mathbf{r}(t)\|=c$, then $\mathbf{r}(t)$ and $\mathbf{r}^{\prime}(t)$ are orthogonal vectors.
- $\mathbf{T}(t)$ has constant norm 1, so $\mathbf{T}(t)$ and $\mathrm{T}^{\prime}(t)$ are orthogonal vectors.
- This implies that $\mathbf{T}^{\prime}(t)$ is perpendicular to the tangent line to $C$ at $t$, so we say that $\mathrm{T}^{\prime}(t)$ is normal to $C$ at $t$.



## UNIT NORMAL VECTORS

- It follows that if $\mathbf{T}^{\prime}(t) \neq 0$, and if we normalize $\mathbf{T}^{\prime}(t)$, then we obtain a unit vector

$$
\mathbf{N}(t)=\frac{\mathbf{T}^{\prime}(t)}{\left\|\mathbf{T}^{\prime}(t)\right\|}
$$

that is normal to $C$ and points in the same direction as $\mathrm{T}^{\prime}(t)$.


## UNIT NORMAL VECTORS

- We call $\mathbf{N}(t)$ the principal unit normal vector to $C$ at $t$, or more simply, the unit normal vector.
- Observe that the unit normal vector is defined only at points where $\mathbf{T}^{\prime}(t) \neq \mathbf{0}$. Unless stated otherwise, we will assume that this condition is satisfied.
- In particular, this excludes straight lines.


## UNIT NORMAL VECTORS

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t)=\langle 3 \cos t, 3 \sin t, 4 t\rangle$.

$$
\begin{aligned}
\mathbf{r}^{\prime}(t) & =\langle-3 \sin t, 3 \cos t, 4\rangle \\
\left\|\mathbf{r}^{\prime}(t)\right\| & =\sqrt{9 \sin ^{2} t+9 \cos ^{2} t+16}=5 \\
\mathbf{T}(t) & =\frac{\langle-3 \sin t, 3 \cos t, 4\rangle}{5}=\left(\frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5}\right\rangle
\end{aligned}
$$

## UNIT NORMAL VECTORS

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t)=\langle 3 \cos t, 3 \sin t, 4 t\rangle$.

$$
\begin{aligned}
\mathbf{T}(t) & =\frac{\langle-3 \sin t, 3 \cos t, 4\rangle}{5}=\left\langle\frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5}\right\rangle \\
\mathbf{T}^{\prime}(t) & =\left\langle\frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0\right\rangle \\
\left\|\mathbf{T}^{\prime}(t)\right\| & =\sqrt{\frac{9}{25} \cos ^{2} t+\frac{9}{25} \sin ^{2} t+0}=\frac{3}{5}
\end{aligned}
$$

## UNIT NORMAL VECTORS

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t)=\langle 3 \cos t, 3 \sin t, 4 t\rangle$.

$$
\begin{aligned}
\mathrm{T}^{\prime}(t) & =\left\langle\frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0\right\rangle \\
\left\|\mathbf{T}^{\prime}(t)\right\| & =\sqrt{\frac{9}{25} \cos ^{2} t+\frac{9}{25} \sin ^{2} t+0}=\frac{3}{5} \\
\mathbf{N}(t) & =\frac{\left(\frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0\right\rangle}{\frac{3}{5}}=\langle-\cos t,-\sin t, 0\rangle
\end{aligned}
$$

## UNIT NORMAL VECTORS

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for $\mathbf{r}(t)=\left\langle\frac{1}{2} t^{2}, \frac{1}{3} t^{3}\right\rangle$ at $t=1$.

$$
\begin{aligned}
& \mathbf{r}^{\prime}(t)=\left\langle t, t^{2}\right\rangle \quad \mathbf{r}^{\prime}(1)=\langle 1,1\rangle \\
& \mathbf{T}(1)=\frac{\mathbf{r}^{\prime}(1)}{\left\|\mathbf{r}^{\prime}(1)\right\|}=\frac{\langle 1,1\rangle}{\sqrt{2}}=\left\langle\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right\rangle \\
& \mathbf{T}(t)=\frac{\mathbf{r}^{\prime}(t)}{\left\|\mathbf{r}^{\prime}(t)\right\|}=\frac{1}{\sqrt{t^{2}+t^{4}}}\left\langle t, t^{2}\right\rangle=\left(t^{2}+t^{4}\right)^{-1 / 2}\left\langle t, t^{2}\right\rangle \\
& \mathbf{T}^{\prime}(t)=\left(t^{2}+t^{4}\right)^{-1 / 2}\langle 1,2 t\rangle-\frac{1}{2}\left(2 t+4 t^{3}\right)\left(t^{2}+t^{4}\right)^{-3 / 2}\left\langle t, t^{2}\right\rangle
\end{aligned}
$$

## UNIT NORMAL VECTORS

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for $\mathbf{r}(t)=\left\langle\frac{1}{2} t^{2}, \frac{1}{3} t^{3}\right\rangle$ at $t=1$.

$$
\begin{aligned}
& \mathrm{T}^{\prime}(t)=\left(t^{2}+t^{4}\right)^{-1 / 2}\langle 1,2 t\rangle-\frac{1}{2}\left(2 t+4 t^{3}\right)\left(t^{2}+t^{4}\right)^{-3 / 2}\left\langle t, t^{2}\right\rangle \\
& \mathrm{T}^{\prime}(1)=\frac{\langle 1,2\rangle}{\sqrt{2}}-\frac{3\langle 1,1\rangle}{2 \sqrt{2}}=\left\langle\frac{-1}{2 \sqrt{2}}, \frac{1}{2 \sqrt{2}}\right\rangle \\
& \left\|\mathrm{T}^{\prime}(1)\right\|=\sqrt{\left(\frac{-1}{2 \sqrt{2}}\right)^{2}+\left(\frac{1}{2 \sqrt{2}}\right)^{2}}=\frac{1}{2} \\
& \mathbf{N}(1)=\frac{\mathrm{T}^{\prime}(1)}{\left\|\mathrm{T}^{\prime}(1)\right\|}=\left\langle\frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right\rangle
\end{aligned}
$$

## BINORMAL VECTORS IN 3 -SPACE

If $C$ is the graph of a vector-valued function $\mathbf{r}(t)$ in 3 -space, then we define the binormal vector to $C$ at $t$ to be

$$
\mathbf{B}(t)=\mathbf{T}(t) \times \mathbf{N}(t)
$$



- It follows from properties of the cross product that $\mathbf{B}(t)$ is orthogonal to both $\mathbf{T}(t)$ and $\mathbf{N}(t)$ and is oriented relative to $\mathbf{T}(t)$ and $\mathbf{N}(t)$ by the right-hand rule.
- $\mathbf{B}(t)$ is unit vector !!.

$$
\|\mathbf{B}(t)\|=\|\mathbf{T}(t) \times \mathbf{N}(t)\|=\|\mathbf{T}(t)\|\|\mathbf{N}(t)\| \sin \frac{\pi}{2}=1
$$

## BINORMAL VECTORS IN 3 -SPACE

Note that $\mathbf{T}(t), \mathbf{N}(t), \mathbf{B}(t)$ are three mutually orthogonal unit vectors.

$$
\begin{aligned}
\mathbf{B}(t) & =\mathbf{T}(t) \times \mathbf{N}(t) \\
\mathbf{N}(t) & =\mathbf{B}(t) \times \mathbf{T}(t) \\
\mathbf{T}(t) & =\mathbf{N}(t) \times \mathbf{B}(t)
\end{aligned}
$$



The binormal $\mathbf{B}(t)$ can be expressed directly in terms of $\mathbf{r}(t)$ as:

$$
\mathbf{B}(t)=\frac{\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)}{\left\|\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)\right\|}
$$



## BINORMAL VECTORS IN 3 -SPACE

Example Find $\mathbf{B}(t)$ for the circular helix $\mathbf{r}(t)=\langle 3 \cos t, 3 \sin t, 4 t\rangle$.

$$
\left.\left.\begin{array}{rl}
\mathbf{T}(t) & =\left\langle\frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5}\right.
\end{array} \right\rvert\, \quad \mathbf{N}(t)=\langle-\cos t,-\sin t, 0\rangle\right)
$$

## BINORMAL VECTORS IN 3 -SPACE

Example Find $\mathbf{B}(t)$ for the circular helix $\mathbf{r}(t)=\langle 3 \cos t, 3 \sin t, 4 t\rangle$.

$$
\begin{aligned}
& \mathbf{r}^{\prime}(t)=\langle-3 \sin t, 3 \cos t, 4\rangle \\
& \mathbf{r}^{\prime \prime}(t)=\langle-3 \cos t,-3 \sin t, 0\rangle \\
& \begin{aligned}
\mathbf{B}(t)=\frac{\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)}{\left\|\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)\right\|} & =\frac{\langle 12 \sin t,-12 \cos t, 9\rangle}{25} \\
& =\left\langle\frac{4}{5} \sin t, \frac{-4}{5} \cos t, \frac{3}{5}\right\rangle
\end{aligned}
\end{aligned}
$$

## Course: Calculus (3)

Chapter: [12]<br>VECTOR-VALUED FUNCTIONS

Section: [12.5]
CURVATURE

## DEFINITION OF CURVATURE

- We will consider the problem of obtaining a numerical measure of how sharply a curve bends.
- For instance, in the figure, the curve bends more sharply at P than at Q and you can say that the curvature is greater at P than at Q .



## DEFINITION OF CURVATURE

You can calculate curvature by calculating the magnitude of the rate of change of the unit tangent vector T with respect to the arc length $s$.


- If $C$ is a straight line (no bend), then the direction of $T$ remains constant.
- If $C$ bends slightly, then $T$ undergoes a gradual change of direction.
- If $C$ bends sharply, then $T$ undergoes a rapid change of direction.


## DEFINITION OF CURVATURE

If $\mathbf{r}(t)$ is a smooth vector-valued function, then for each value of $t$ at which $\mathbf{T}^{\prime}(t)$ and $\mathbf{r}^{\prime \prime}(t)$ exist, the curvature $\kappa$ can be expressed as

$$
\kappa(t)=\frac{\left\|\mathbf{T}^{\prime}(t)\right\|}{\left\|\mathbf{r}^{\prime}(t)\right\|}=\frac{\left\|\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)\right\|}{\left\|\mathbf{r}^{\prime}(t)\right\|^{3}}
$$

Example Show that the curvature of a circle of radius $R$ is $\kappa=\frac{1}{R}$.
(1) $\kappa(t)=\frac{\left\|\mathbf{T}^{\prime}(t)\right\|}{\left\|\mathbf{r}^{\prime}(t)\right\|}$

## DEFINITION OF CURVATURE

Example Show that the curvature of a circle of radius $R$ is $\kappa=\frac{1}{R}$.
(1) $\kappa(t)=\frac{\left\|\mathbf{T}^{\prime}(t)\right\|}{\left\|\mathbf{r}^{\prime}(t)\right\|} \quad \mathbf{r}(t)=R \cos t \mathbf{i}+R \sin t \mathbf{j} \quad t \in[0,2 \pi]$

$$
\mathbf{r}^{\prime}(t)=-R \sin t \mathbf{i}+R \cos t \mathbf{j}
$$

$$
\mathbf{T}(t)=\frac{\mathbf{r}^{\prime}(t)}{\left\|\mathbf{r}^{\prime}(t)\right\|}=\frac{\langle-R \sin t, R \cos t\rangle}{\sqrt{(-R \sin t)^{2}+(R \cos t)^{2}}}=\langle-\sin t, \cos t\rangle
$$

$$
\mathbf{T}^{\prime}(t)=\langle-\cos t,-\sin t\rangle
$$

$$
\kappa(t)=\frac{\sqrt{(-\cos t)^{2}+(-\sin t)^{2}}}{\sqrt{(-R \sin t)^{2}+(R \cos t)^{2}}}=\frac{1}{R}
$$

## DEFINITION OF CURVATURE

Example Show that the curvature of a circle of radius $R$ is $\kappa=\frac{1}{R}$.
(2) $\kappa(t)=\frac{\left\|\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)\right\|}{\left\|\mathbf{r}^{\prime}(t)\right\|^{3}} \quad \mathbf{r}(t)=R \cos t \mathbf{i}+R \sin t \mathbf{j}+0 \mathbf{k} \quad t \in[0,2 \pi]$
$\mathbf{r}^{\prime}(t)=-R \sin t \mathbf{i}+R \cos t \mathbf{j}+0 \mathbf{k}$
$\mathbf{r}^{\prime \prime}(t)=-R \cos t \mathbf{i}-R \sin t \mathbf{j}+0 \mathbf{k}$

$$
\begin{aligned}
& \mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)=\left|\begin{array}{ccc}
\mathbf{i} & \mathbf{j} & \mathbf{k} \\
-R \sin t & R \cos t & 0 \\
-R \cos t & -R \sin t & 0
\end{array}\right|=R^{2} \mathbf{k} \\
&\left\|\mathbf{r}^{\prime}(t) \times \mathbf{r}^{\prime \prime}(t)\right\|=R^{2} \\
&\left\|\mathbf{r}^{\prime}(t)\right\|=R
\end{aligned} \quad \kappa(t)=\frac{R^{2}}{R^{3}}=\frac{1}{R} .
$$

