Course: Calculus (3)

Chapter: [12] VECTOR-VALUED FUNCTIONS

Section: [12.1] INTRODUCTION TO VECTOR-VALUED FUNCTIONS

IN THIS CHAPTER

 \checkmark We will consider *functions whose values are* vectors.



Functions that associate vectors with real numbers.

✓ In this section we will discuss more general parametric curves, and we will show how vector notation can be used to express parametric equations in a more compact form.

VECTOR-VALUED FUNCTIONS

A function of the form

 $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ $= \langle f(t), g(t), h(t) \rangle$

is a vector-valued function, where the component functions f, g and h are real-valued functions of the parameter t.



PARAMETRIC CURVES IN 3 - SPACE

Example The parametric equations

$$x = 1 - t$$
$$y = 3t$$
$$z = 2t$$

represent a line in 3 —space that passes through the point (1,0,0) and is parallel to the vector $\langle -1, 3, 2 \rangle$.

$$\mathbf{r}(t) = (1-t)\mathbf{i} + 3t\,\mathbf{j} + 2t\,\mathbf{k}$$
$$= \langle 1-t, 3t, 2t \rangle$$



PARAMETRIC CURVES IN 3 – SPACE

Example Describe the parametric curve represented by the equations



$$x = 10 \cos t$$
$$y = 10 \sin t$$
$$z = t$$



Circular HELIX

 $\mathbf{r}(t) = 10 \cos t \,\mathbf{i} + 10 \sin t \,\mathbf{j} + t \mathbf{k}$ $= \langle 10 \cos t \,, 10 \sin t \,, t \rangle$

VECTOR-VALUED FUNCTIONS

The domain of a vector-valued function $\mathbf{r}(t)$ is the set of allowable values for t.

NOTE Usual reasons to restrict a domain:

- 1. Avoid division by 0.
- 2. Avoid even roots of negative numbers.
- 3. Avoid logarithms of negative numbers or 0.

VECTOR-VALUED FUNCTIONS

Example Find the natural domain of $\mathbf{r}(t) = \ln|t - 1|\mathbf{i} + e^t\mathbf{j} + \sqrt{t}\mathbf{k}$

$$x(t) = \ln|t-1|$$

 $rac{1}{rac{1}{2}}$ Domain = $\mathbb{R} - \{1\}$



 $z(t) = \sqrt{t}$ \square Domain = $[0, \infty)$

 \therefore The domain of $\mathbf{r}(t)$ is the *intersection of these sets*.



Course: Calculus (3)

Chapter: [12] VECTOR-VALUED FUNCTIONS

Section: [12.2] CALCULUS OF VECTOR-VALUED FUNCTIONS

- Many techniques and definitions used in the calculus of realvalued functions can be applied to vector-valued functions.
- For instance, you can add and subtract vector-valued functions, multiply a vector-valued function by a scalar, take the limit of a vector-valued function, differentiate a vectorvalued function, and so on.

$$\mathbf{r}_{1}(t) + \mathbf{r}_{2}(t) = [f_{1}(t)\mathbf{i} + g_{1}(t)\mathbf{j}] + [f_{2}(t)\mathbf{i} + g_{2}(t)\mathbf{j}]$$
$$= [f_{1}(t) + f_{2}(t)]\mathbf{i} + [g_{1}(t) + g_{2}(t)]\mathbf{j}.$$

$$\mathbf{r}_{1}(t) - \mathbf{r}_{2}(t) = [f_{1}(t)\mathbf{i} + g_{1}(t)\mathbf{j}] - [f_{2}(t)\mathbf{i} + g_{2}(t)\mathbf{j}]$$
$$= [f_{1}(t) - f_{2}(t)]\mathbf{i} + [g_{1}(t) - g_{2}(t)]\mathbf{j}.$$

$$c\mathbf{r}(t) = c[f_1(t)\mathbf{i} + g_1(t)\mathbf{j}]$$
$$= cf_1(t)\mathbf{i} + cg_1(t)\mathbf{j}.$$

$$\frac{\mathbf{r}(t)}{c} = \frac{\left[f_1(t)\mathbf{i} + g_1(t)\mathbf{j}\right]}{c}, \quad c \neq 0$$
$$= \frac{f_1(t)}{c}\mathbf{i} + \frac{g_1(t)}{c}\mathbf{j}.$$

If **r** is a vector-valued function such that $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$, then $\lim_{t \to a} \mathbf{r}(t) = \left[\lim_{t \to a} f(t)\right]\mathbf{i} + \left[\lim_{t \to a} g(t)\right]\mathbf{j} + \left[\lim_{t \to a} h(t)\right]\mathbf{k}$

provided f, g, and h have limits as $t \to a$.

Example If
$$\mathbf{r}(t) = \frac{3}{t^2}\mathbf{i} + \frac{\ln t}{t^2 - 1}\mathbf{j} + \cos(\pi t)\mathbf{k}$$
, find $\lim_{t \to 1} \mathbf{r}(t)$.

$$\lim_{t \to 1} \mathbf{r}(t) = \langle 3, \frac{1}{2}, -1 \rangle \qquad \qquad \lim_{t \to 1} \frac{3}{t^2} = 3$$

$$= 3\mathbf{i} + \frac{1}{2}\mathbf{j} - \mathbf{k} \qquad \qquad \lim_{t \to 1} \frac{\ln t}{t^2 - 1} = \lim_{t \to 1} \frac{1/t}{2t} = \frac{1}{2}$$

$$\lim_{t \to 1} \cos(\pi t) = -1$$

Example If
$$\mathbf{r}(t) = \frac{2t^2 - 1}{t^2 + t}\mathbf{i} + \sin\left(\frac{1}{t}\right)\mathbf{j} + te^{-t}\mathbf{k}$$
, find $\lim_{t \to \infty} \mathbf{r}(t)$.
$$\lim_{t \to \infty} \mathbf{r}(t) = \langle 2, 0, 0 \rangle = 2\mathbf{i}$$

$$\lim_{t \to \infty} \frac{2t^2 - 1}{t^2 + t} = 2 \qquad \qquad \lim_{t \to \infty} te^{-t} = 0 \cdot \infty$$
$$= \lim_{t \to \infty} \frac{t}{e^t} = \lim_{t \to \infty} \frac{1}{e^t} = 0$$

A vector-valued function **r** is **continuous at the point** given by t = a when the limit of $\mathbf{r}(t)$ exists as $t \rightarrow a$ and

 $\lim_{t\to a}\mathbf{r}(t)=\mathbf{r}(a).$

A vector-valued function **r** is **continuous on an interval** *I* when it is continuous at every point in the interval.

Example The vector-valued function $\mathbf{r}(t) = t^2\mathbf{i} + \frac{1}{t^2-1}\mathbf{j} + t\mathbf{k}$, is discontinuous at $t = \pm 1$.

It is continuous for all $t \in \mathbb{R} - \{-1, 1\}$

• The derivative of a vector-valued function is *defined by a limit* like that

for the derivative of a real-valued function.

$$\mathbf{r}'(t) = \lim_{h \to 0} \frac{\mathbf{r}(t+h) - \mathbf{r}(t)}{h}$$

• The derivative of $\mathbf{r}(t)$ can be *expressed as*

$$\frac{d}{dt}[\mathbf{r}(t)], \quad \frac{d\mathbf{r}}{dt}, \quad \mathbf{r}'(t), \quad \mathbf{r}'$$

• Keep in mind that $\mathbf{r}(t)$ is a *vector*, not a number, and hence *has a*

magnitude and a direction for each value of t, except if $\mathbf{r}(t) = \mathbf{0}$.

Suppose that C is the graph of a vector-valued function $\mathbf{r}(t)$ and that $\mathbf{r}'(t)$ exists and is nonzero for a given value of t.

If the vector $\mathbf{r}'(t)$ is positioned with its initial point at the terminal point of the radius vector $\mathbf{r}(t)$, then $\mathbf{r}'(t)$ is tangent to *C* and points in the direction of increasing parameter.



If $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$, where *f*, *g*, and *h* are differentiable functions of *t*, then

 $\mathbf{r}'(t) = f'(t)\mathbf{i} + g'(t)\mathbf{j} + h'(t)\mathbf{k}.$

Example For the vector-valued function $\mathbf{r}(t) = t\mathbf{i} + (t^2 + 2)\mathbf{j}$, find $\mathbf{r}'(1)$.

$$\mathbf{r}'(t) = \mathbf{i} + 2t\mathbf{j}$$
$$\mathbf{r}'(1) = \mathbf{i} + 2\mathbf{j}$$



Example For the vector-valued function $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + 2t \mathbf{k}$, find: **1** r'(t) $\mathbf{r}'(t) = -\sin t \, \mathbf{i} + \cos t \, \mathbf{j} + 2\mathbf{k}$ $\mathbf{r}''(t) = -\cos t \,\mathbf{i} - \sin t \,\mathbf{j}$ **2** r''(t)3 $\mathbf{r}'(t) \cdot \mathbf{r}''(t)$ $\mathbf{r}'(t) \cdot \mathbf{r}''(t) = \sin t \cos t - \cos t \sin t = 0$ 4 $\mathbf{r}'(t) \times \mathbf{r}''(t)$ $\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{J} & \mathbf{k} \\ -\sin t & \cos t & 2 \\ -\cos t & -\sin t & 0 \end{vmatrix} = 2\sin t \,\mathbf{i} - 2\cos t \,\mathbf{j} + \mathbf{k}$

DERIVATIVE RULES

1.
$$\frac{d}{dt} [c\mathbf{r}(t)] = c\mathbf{r}'(t)$$

2.
$$\frac{d}{dt} [\mathbf{r}(t) \pm \mathbf{u}(t)] = \mathbf{r}'(t) \pm \mathbf{u}'(t)$$

3.
$$\frac{d}{dt} [w(t)\mathbf{r}(t)] = w(t)\mathbf{r}'(t) + w'(t)\mathbf{r}(t)$$

4.
$$\frac{d}{dt} [\mathbf{r}(t) \cdot \mathbf{u}(t)] = \mathbf{r}(t) \cdot \mathbf{u}'(t) + \mathbf{r}'(t) \cdot \mathbf{u}(t)$$

5.
$$\frac{d}{dt} [\mathbf{r}(t) \times \mathbf{u}(t)] = \mathbf{r}(t) \times \mathbf{u}'(t) + \mathbf{r}'(t) \times \mathbf{u}(t)$$

6.
$$\frac{d}{dt} [\mathbf{r}(w(t))] = \mathbf{r}'(w(t))w'(t)$$

7. If $\mathbf{r}(t) \cdot \mathbf{r}(t) = c$, then $\mathbf{r}(t) \cdot \mathbf{r}'(t) = 0$.

DERIVATIVE RULES

Example For $\mathbf{u}(t) = \frac{1}{t}\mathbf{i} - \mathbf{j} + \ln t \mathbf{k}$ and $\mathbf{v}(t) = t^2\mathbf{i} - 2t\mathbf{j} + \mathbf{k}$ then: 1 $\frac{d}{dt}[\mathbf{u}(t)\cdot\mathbf{v}(t)] = \mathbf{u}(t)\cdot\mathbf{v}'(t) + \mathbf{u}'(t)\cdot\mathbf{v}(t)$ $= \left\langle \frac{1}{t}, -1, \ln t \right\rangle \cdot \left\langle 2t, -2, 0 \right\rangle + \left\langle \frac{-1}{t^2}, 0, \frac{1}{t} \right\rangle \cdot \left\langle t^2, -2t, 1 \right\rangle$ $= (2+2+0) + \left(-1+0+\frac{1}{t}\right)$ $= 3 + \frac{1}{t}$

DERIVATIVE RULES

Example For $\mathbf{u}(t) = \frac{1}{t}\mathbf{i} - \mathbf{j} + \ln t \mathbf{k}$ and $\mathbf{v}(t) = t^2\mathbf{i} - 2t\mathbf{j} + \mathbf{k}$ then: 2 $\frac{d}{dt}[\mathbf{v}(t) \times \mathbf{v}'(t)] = \mathbf{v}(t) \times \mathbf{v}''(t) + \mathbf{v}'(t) \times \mathbf{v}'(t)$ $= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ t^2 & -2t & 1 \\ 2 & 0 & 0 \end{vmatrix} + \mathbf{0}$

 $= 2\mathbf{j} + 4t\mathbf{k}$

TANGENT LINES TO GRAPHS OF VECTOR-VALUED FUNCTIONS

Example Find parametric equations of the tangent line to the circular helix $\mathbf{r}(t) = \cos t \, \mathbf{i} + \sin t \, \mathbf{j} + t \, \mathbf{k}$ at the point where $t = \pi$.



DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

In general, we have

$$\int_{a}^{b} \mathbf{r}(t) dt = \left(\int_{a}^{b} x(t) dt \right) \mathbf{i} + \left(\int_{a}^{b} y(t) dt \right) \mathbf{j} + \left(\int_{a}^{b} z(t) dt \right) \mathbf{k}$$

Example Let $\mathbf{r}(t) = t^2 \mathbf{i} + e^t \mathbf{j} - 2\cos(\pi t) \mathbf{k}$. Then

$$\int_0^1 \mathbf{r}(t) dt = \left(\int_0^1 t^2 dt \right) \mathbf{i} + \left(\int_0^1 e^t dt \right) \mathbf{j} - \left(\int_0^1 2 \cos \pi t \, dt \right) \mathbf{k}$$
$$= \frac{t^3}{3} \Big]_0^1 \mathbf{i} + e^t \Big]_0^1 \mathbf{j} - \frac{2}{\pi} \sin \pi t \Big]_0^1 \mathbf{k} = \frac{1}{3} \mathbf{i} + (e-1) \mathbf{j}$$

DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

Example
$$\int (2t\mathbf{i} + 3t^2\mathbf{j}) dt = \left(\int 2t dt\right)\mathbf{i} + \left(\int 3t^2 dt\right)\mathbf{j}$$

$$= (t^2 + C_1)\mathbf{i} + (t^3 + C_2)\mathbf{j}$$
$$= (t^2\mathbf{i} + t^3\mathbf{j}) + (C_1\mathbf{i} + C_2\mathbf{j}) = (t^2\mathbf{i} + t^3\mathbf{j}) + \mathbf{C}$$

DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

Example Find $\mathbf{r}(t)$ given that $\mathbf{r}'(t) = \langle 3, 2t \rangle$ and $\mathbf{r}(1) = \langle 2, 5 \rangle$.

$$\mathbf{r}(t) = \int \mathbf{r}'(t)dt = \int \langle 3,2t \rangle dt = \langle 3t,t^2 \rangle + \mathbf{C}$$

But $\mathbf{r}(1) = \langle 2, 5 \rangle$ So $\mathbf{r}(t) = \langle 3t, t^2 \rangle + \langle -1, 4 \rangle$ $\langle 3, 1 \rangle + \mathbf{C} = \langle 2, 5 \rangle$ $\mathbf{r}(t) = \langle 3t - 1, t^2 + 4 \rangle$ $\mathbf{C} = \langle -1, 4 \rangle$ Course: Calculus (3)

Chapter: [12] VECTOR-VALUED FUNCTIONS

Section: [12.3] CHANGE OF PARAMETER; ARC LENGTH

SMOOTH PARAMETRIZATIONS

• We will say that a curve represented by $\mathbf{r}(t)$ is *smoothly parametrized*

by $\mathbf{r}(t)$, or that $\mathbf{r}(t)$ is a smooth function of t if:

 \checkmark **r**'(*t*) is continuous, and

✓ $\mathbf{r}'(t) \neq \mathbf{0}$ for any allowable value of *t*.

 Geometrically, this means that a smoothly parametrized curve can have no abrupt (مفاجئ) changes in direction as the parameter increases.

SMOOTH PARAMETRIZATIONS

Example Determine whether the following vector-valued functions are smooth.

1
$$\mathbf{r}(t) = a \cos t \mathbf{i} + a \sin t \mathbf{j} + ct \mathbf{k}$$
 $a > 0, c > 0$

$$\mathbf{r}'(t) = -a\sin t\,\mathbf{i} + a\cos t\,\mathbf{j} + c\mathbf{k}$$

- ✓ The components are continuous functions, and
- \checkmark there is no value of t for which all three of them are zero.
- ✓ So $\mathbf{r}(t)$ is a smooth function.

SMOOTH PARAMETRIZATIONS

Example Determine whether the following vector-valued functions are smooth.

$$\mathbf{2} \mathbf{r}(t) = t^2 \mathbf{i} + t^3 \mathbf{j}$$

$$\mathbf{r}'(t) = 2t\mathbf{i} + 3t^2\mathbf{j}$$

✓ The components are continuous

- ✓ they are both equal to zero if t = 0.
- ✓ So, $\mathbf{r}(t)$ is NOT a smooth function.



ARC LENGTH FROM THE VECTOR VIEWPOINT

If C is the graph of a smooth vector-valued function $\mathbf{r}(t)$, then its arc length ℓ from t = a to t = b is

$$\ell = \int_{a}^{b} \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$ from t = 0 to $t = \pi$.

ARC LENGTH FROM THE VECTOR VIEWPOINT

$$\ell = \int_{a}^{b} \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$ from t = 0 to $t = \pi$.

$$\mathbf{r}'(t) = \langle -\sin t, \cos t, 1 \rangle \qquad \ell =$$
$$\|\mathbf{r}'(t)\| = \sqrt{(-\sin t)^2 + \cos^2 t + 1} = \sqrt{2}$$

$$\ell = \int_{0}^{\pi} ||\mathbf{r}'(t)|| dt$$
$$= \int_{0}^{\pi} \sqrt{2} dt$$
$$= \sqrt{2} \pi$$

π

Course: Calculus (3)

Chapter: [12] VECTOR-VALUED FUNCTIONS

Section: [12.4] UNIT TANGENT, NORMAL, AND BINORMAL VECTORS

UNIT TANGENT VECTORS

- Recall that if *C* is the graph of a *smooth* vector-valued function $\mathbf{r}(t)$, then the vector $\mathbf{r}'(t)$ is: **A** y **T**(t)
 - \checkmark nonzero, tangent to C, and
 - \checkmark points in the direction of increasing parameter.
- Thus, by normalizing $\mathbf{r}'(t)$ we obtain a unit vector

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$$

that is tangent to C and points in the direction of increasing parameter.

• We call $\mathbf{T}(t)$ the unit tangent vector to C at t.



UNIT TANGENT VECTORS

Example Find the unit tangent vector to the graph of $\mathbf{r}(t) = t^2\mathbf{i} + t^3\mathbf{j}$ at the point where t = 2. 10 (4, 8) $\mathbf{T}(2) = \frac{1}{\sqrt{10}}\mathbf{i} + \frac{3}{\sqrt{10}}\mathbf{j}$ $r'(t) = 2ti + 3t^2j$ r'(2) = 4i + 12j $\mathbf{T}(2) = \frac{\mathbf{r}'(2)}{\|\mathbf{r}'(2)\|}$ $\mathbf{r}(t) = t^2 \mathbf{i} + t^3 \mathbf{i}$ $=\frac{\ddot{4}\mathbf{i}+\ddot{1}\ddot{2}\mathbf{j}}{\sqrt{160}}=\frac{1}{\sqrt{10}}\mathbf{i}+\frac{3}{\sqrt{10}}\mathbf{j}$

• Recall if $||\mathbf{r}(t)|| = c$, then $\mathbf{r}(t)$ and

 $\mathbf{r}'(t)$ are orthogonal vectors.

• $\mathbf{T}(t)$ has constant norm 1, so $\mathbf{T}(t)$ and

 $\mathbf{T}'(t)$ are orthogonal vectors.

• This implies that $\mathbf{T}'(t)$ is perpendicular

to the tangent line to C at t, so we say

that $\mathbf{T}'(t)$ is *normal* to C at t.



• It follows that if $\mathbf{T}'(t) \neq \mathbf{0}$, and if we normalize $\mathbf{T}'(t)$, then we obtain a unit vector

$$\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$$

that is normal to C and points in the same direction as $\mathbf{T}'(t)$.



• We call $\mathbf{N}(t)$ the *principal unit normal vector to C at t*, or more simply,

the *unit normal vector*.

• Observe that the unit normal vector is defined only at points where

 $\mathbf{T}'(t) \neq \mathbf{0}$. Unless stated otherwise, we will assume that this condition

is satisfied.

• In particular, this excludes straight lines.

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$.

$$\mathbf{r}'(t) = \langle -3\sin t, 3\cos t, 4 \rangle$$

$$\|\mathbf{r}'(t)\| = \sqrt{9}\sin^2 t + 9\cos^2 t + 16 = 5$$
$$\mathbf{T}(t) = \frac{\langle -3\sin t, 3\cos t, 4 \rangle}{5} = \left\langle \frac{-3}{5}\sin t, \frac{3}{5}\cos t, \frac{4}{5} \right\rangle$$

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$.

$$\mathbf{T}(t) = \frac{\langle -3\sin t, 3\cos t, 4 \rangle}{5} = \left\langle \frac{-3}{5}\sin t, \frac{3}{5}\cos t, \frac{4}{5}\right\rangle$$
$$\mathbf{T}'(t) = \left\langle \frac{-3}{5}\cos t, \frac{-3}{5}\sin t, 0 \right\rangle$$
$$\|\mathbf{T}'(t)\| = \sqrt{\frac{9}{25}\cos^2 t + \frac{9}{25}\sin^2 t + 0} = \frac{3}{5}$$

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for the circular helix $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$.

$$\mathbf{T}'(t) = \left\langle \frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0 \right\rangle$$

$$\|\mathbf{T}'(t)\| = \sqrt{\frac{9}{25}\cos^2 t + \frac{9}{25}\sin^2 t + 0} = \frac{3}{5}$$

$$\mathbf{N}(t) = \frac{\left\langle \frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0 \right\rangle}{\frac{3}{5}} = \left\langle -\cos t, -\sin t, 0 \right\rangle$$

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for $\mathbf{r}(t) = \left\langle \frac{1}{2}t^2, \frac{1}{3}t^3 \right\rangle$ at t = 1.

$$\mathbf{r}'(t) = \langle t, t^2 \rangle \qquad \mathbf{r}'(1) = \langle 1, 1 \rangle$$

$$\mathbf{T}(1) = \frac{\mathbf{r}'(1)}{\|\mathbf{r}'(1)\|} = \frac{\langle 1, 1 \rangle}{\sqrt{2}} = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$$

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{1}{\sqrt{t^2 + t^4}} \langle t, t^2 \rangle = (t^2 + t^4)^{-1/2} \langle t, t^2 \rangle$$

$$\mathbf{T}'(t) = (t^2 + t^4)^{-1/2} \langle 1, 2t \rangle - \frac{1}{2} (2t + 4t^3) (t^2 + t^4)^{-3/2} \langle t, t^2 \rangle$$

Example Find $\mathbf{T}(t)$ and $\mathbf{N}(t)$ for $\mathbf{r}(t) = \left\langle \frac{1}{2}t^2, \frac{1}{3}t^3 \right\rangle$ at t = 1. $\mathbf{T}'(t) = (t^2 + t^4)^{-1/2} \langle 1, 2t \rangle - \frac{1}{2} (2t + 4t^3) (t^2 + t^4)^{-3/2} \langle t, t^2 \rangle$ $\mathbf{T}'(1) = \frac{\langle 1,2 \rangle}{\sqrt{2}} - \frac{3\langle 1,1 \rangle}{2\sqrt{2}} = \left\{ \frac{-1}{2\sqrt{2}}, \frac{1}{2\sqrt{2}} \right\}$ $\|\mathbf{T}'(1)\| = \sqrt{\left(\frac{-1}{2\sqrt{2}}\right)^2 + \left(\frac{1}{2\sqrt{2}}\right)^2} = \frac{1}{2}$ $\mathbf{N}(1) = \frac{\mathbf{T}'(1)}{\|\mathbf{T}'(1)\|} = \left\langle \frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\rangle$

BINORMAL VECTORS IN 3 - SPACE

If C is the graph of a vector-valued function $\mathbf{r}(t)$ in 3 – space, then we define the *binormal vector* to C at t to be

 $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$



- It follows from properties of the cross product that $\mathbf{B}(t)$ is orthogonal to both $\mathbf{T}(t)$ and $\mathbf{N}(t)$ and is oriented relative to $\mathbf{T}(t)$ and $\mathbf{N}(t)$ by the right-hand rule.
- $\mathbf{B}(t)$ is unit vector !!.

 $\|\mathbf{B}(t)\| = \|\mathbf{T}(t) \times \mathbf{N}(t)\| = \|\mathbf{T}(t)\| \|\mathbf{N}(t)\| \sin \frac{\pi}{2} = 1$

BINORMAL VECTORS IN 3 - SPACE

Note that $\mathbf{T}(t)$, $\mathbf{N}(t)$, $\mathbf{B}(t)$ are three *mutually orthogonal unit vectors*.

 $B(t) = T(t) \times N(t)$ $N(t) = B(t) \times T(t)$ $T(t) = N(t) \times B(t)$

The binormal $\mathbf{B}(t)$ can be expressed directly in terms of $\mathbf{r}(t)$ as:

$$\mathbf{B}(t) = \frac{\mathbf{r}'(t) \times \mathbf{r}''(t)}{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}$$





BINORMAL VECTORS IN 3 – SPACE

Example Find **B**(*t*) for the circular helix $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$.

$$\mathbf{T}(t) = \left\langle \frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5} \right\rangle \qquad \mathbf{N}(t) = \langle -\cos t, -\sin t, 0 \rangle$$

$$B(t) = T(t) \times N(t) = \begin{vmatrix} i & j & k \\ -\frac{3}{5} \sin t & \frac{3}{5} \cos t & \frac{4}{5} \\ -\cos t & -\sin t & 0 \end{vmatrix}$$
$$= \left(\frac{4}{5} \sin t, \frac{-4}{5} \cos t, \frac{3}{5} \right)$$

BINORMAL VECTORS IN 3 – SPACE

Example Find **B**(*t*) for the circular helix $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$.

$$\mathbf{r}'(t) = \langle -3\sin t, 3\cos t, 4 \rangle$$

$$\mathbf{r}''(t) = \langle -3\cos t, -3\sin t, 0 \rangle$$

$$\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -3\sin t & 3\cos t & 4 \\ -3\cos t & -3\sin t & 0 \end{vmatrix} = \langle 12\sin t, -12\cos t, 9 \rangle$$

$$\mathbf{B}(t) = \frac{\mathbf{r}'(t) \times \mathbf{r}''(t)}{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|} = \frac{\langle 12\sin t, -12\cos t, 9 \rangle}{25}$$

$$= \left\langle \frac{4}{5}\sin t, \frac{-4}{5}\cos t, \frac{3}{5} \right\rangle$$

Course: Calculus (3)

Chapter: [12] VECTOR-VALUED FUNCTIONS

Section: [12.5] CURVATURE

- We will consider the problem of obtaining a *numerical measure of how* sharply a curve bends.
- For instance, in the figure, the curve bends more sharply at P than at Q and you can say that the curvature is greater at P than at Q.



You can calculate curvature by calculating the magnitude of the rate of change of the unit tangent vector **T** with respect to the arc length s.



- If *C* bends slightly, then **T** undergoes a gradual change of direction.
- If *C* bends sharply, then **T** undergoes a rapid change of direction.

If $\mathbf{r}(t)$ is a smooth vector-valued function, then for each value of t at which $\mathbf{T}'(t)$ and $\mathbf{r}''(t)$ exist, the curvature κ can be expressed as

$$\kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$$

Example Show that the curvature of a circle of radius R is $\kappa = \frac{1}{R}$. 1 $\kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|}$

 $||\mathbf{m}/(\mathbf{L})||$

Example Show that the curvature of a circle of radius R is $\kappa = \frac{1}{R}$.

1
$$\kappa(t) = \frac{\|\mathbf{I}^{T}(t)\|}{\|\mathbf{r}'(t)\|}$$
 $\mathbf{r}(t) = R\cos t\,\mathbf{i} + R\sin t\,\mathbf{j}$ $t \in [0,2\pi]$
 $\mathbf{r}'(t) = -R\sin t\,\mathbf{i} + R\cos t\,\mathbf{j}$

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{\langle -R\sin t, R\cos t \rangle}{\sqrt{(-R\sin t)^2 + (R\cos t)^2}} = \langle -\sin t, \cos t \rangle$$

$$\mathbf{T}'(t) = \langle -\cos t \, , -\sin t \rangle$$

$$\kappa(t) = \frac{\sqrt{(-\cos t)^2 + (-\sin t)^2}}{\sqrt{(-R\sin t)^2 + (R\cos t)^2}} = \frac{1}{R}$$

Example Show that the curvature of a circle of radius R is $\kappa = \frac{1}{R}$. 2 $\kappa(t) = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$ $\mathbf{r}(t) = R\cos t\,\mathbf{i} + R\sin t\,\mathbf{j} + 0\mathbf{k}$ $t \in [0, 2\pi]$ $\mathbf{r}'(t) = -R \sin t \, \mathbf{i} + R \cos t \, \mathbf{j} + 0 \mathbf{k}$ $\mathbf{r}''(t) = -R\cos t\,\mathbf{i} - R\sin t\,\mathbf{j} + 0\mathbf{k}$ $\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -R\sin t & R\cos t & 0 \\ -R\cos t & -R\sin t & 0 \end{vmatrix} = R^2 \mathbf{k}$ $\|\mathbf{r}'(t) \times \mathbf{r}''(t)\| = R^2$ $\kappa(t) = \frac{R^2}{R^3} = \frac{1}{R}$ $\|\mathbf{r}'(t)\| = R$