Course: Calculus (4)

Chapter: [15] TOPICS IN VECTOR CALCULUS

Section: [15.1] VECTOR FIELDS

VECTOR FIELDS

• A **vector field** in a plane is a function that associates with each point *P*

in the plane a unique vector $\mathbf{F}(P)$ parallel to the plane.

$$\mathbf{F}(x,y) = M(x,y)\,\mathbf{i} + N(x,y)\,\mathbf{j}$$



VECTORS VIEWED GEOMETRICALLY

A **Vector** in 2-space or 3-space; is an **arrow** with direction and length (magnitude).



Two vectors are equal if they are translations of one another.



VECTORS VIEWED GEOMETRICALLY

Because vectors are **not** affected by translation, the initial point of a vector \mathbf{v} can be *moved* to any convenient point A by making an appropriate *translation*.



VECTORS VIEWED GEOMETRICALLY

Example Draw the vector $\mathbf{v} = \langle 2, 1 \rangle$ from the point (-1, 2).

End Point = Initial Point + \mathbf{v} = (-1,2) + (2,1) = (1,3)



GRAPHICAL REPRESENTATIONS OF VECTOR FIELDS

Example Sketch some vectors in the vector field $\mathbf{F}(x, y) = x \mathbf{i}$.





GRAPHICAL REPRESENTATIONS OF VECTOR FIELDS

Example Sketch some vectors in the vector field $\mathbf{F}(x, y) = -y \mathbf{i} + x \mathbf{j}$.

End Point = Initial Point + \mathbf{F} = (x, y) + (-y, x)=(x-y,x+y) $\|\mathbf{F}\| = c \Rightarrow \sqrt{(-y)^2 + x^2} = c$ $\Rightarrow x^2 + y^2 = c^2$



LEVEL CURVES

The set of points in the plane where a function f(x, y) has a constant value f(x, y) = c is called a **level curve** of f.





DIRECTIONAL DERIVATIVES

- To determine the slope at a point on a surface, you will define a new type of derivative called a *directional derivative*.
- To do this is to use a unit vector

 $\mathbf{u} = u_1 \mathbf{i} + u_2 \mathbf{j}$

that has its initial point at (x_0, y_0)

and points in the desired direction.



$$D_{\mathbf{u}}f(x_0, y_0) = f_x(x_0, y_0)u_1 + f_y(x_0, y_0)u_2$$

THE GRADIENT

(a) If f is a function of x and y, then the *gradient of f* is defined by

$$\nabla f(x, y) = f_x(x, y)\mathbf{i} + f_y(x, y)\mathbf{j}$$

(b) If f is a function of x, y, and z, then the *gradient of f* is defined by

$$\nabla f(x, y, z) = f_x(x, y, z)\mathbf{i} + f_y(x, y, z)\mathbf{j} + f_z(x, y, z)\mathbf{k}$$

If $\nabla f \neq \mathbf{0}$ at P, then among all possible directional derivatives of f at P, the derivative in the direction of ∇f at P has the largest value. The value of this largest directional derivative is $\|\nabla f\|$ at P.

GRADIENT FIELDS

If f(x, y) is a function of two variables, then the gradient of f is given by

$$\nabla f = \langle f_x, f_y \rangle = f_x \mathbf{i} + f_y \mathbf{j}$$

- This formula defines a vector field in 2-space called the gradient field of *f*.
- At each point in a gradient field where the gradient is nonzero, the vector points in the direction in which the rate of increase of

f is maximum.

GRADIENT FIELDS

Example Sketch the gradient field of f(x, y) = x + y.

 $\nabla f = \mathbf{i} + \mathbf{j}$

End Point = Initial Point + ∇f = (x, y) + (1, 1)= (x + 1, y + 1)

Draw some level curves.

Note that at each point, ∇f is normal to the level curve of f through the point.



CONSERVATIVE FIELDS AND POTENTIAL FUNCTIONS

If **F** is an arbitrary vector field in 2 —space or 3 —space, we can ask whether it is the gradient field of some function f, and if so, how we can find f.

Definition: A vector field **F** in 2 — space or 3 — space is said to be **conservative** in a region if it is the gradient field for some function f in that region, that is, if

$$\mathbf{F} = \nabla f$$

The function *f* is called a **potential function for F** in the region.

CONSERVATIVE FIELDS AND POTENTIAL FUNCTIONS

Example The vector field given by $\mathbf{F}(x, y) = 2x \mathbf{i} + y \mathbf{j}$ is conservative.

To see this, consider the potential function $f(x, y) = x^2 + \frac{1}{2}y^2$. Because

$$\nabla f = 2x \mathbf{i} + y \mathbf{j} = \mathbf{F}$$

it follows that **F** is conservative.

TEST FOR CONSERVATIVE VECTOR FIELD IN THE PLANE

Let M(x, y) and N(x, y) have continuous first partial derivatives on an open disk R. The vector field $\mathbf{F}(x, y) = M \mathbf{i} + N \mathbf{j}$ is conservative if and only if

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Example Find α such that $\mathbf{F}(x, y) = (4x^2 + \alpha xy)\mathbf{i} + (3y^2 + 4x^2)\mathbf{j}$ is a gradient field (conservative).

$$M = 4x^{2} + \alpha xy$$

$$N = 3y^{2} + 4x^{2}$$

F is a gradient filed $\Leftrightarrow M_{y} = N_{x}$
 $\Leftrightarrow \alpha x = 8x$

 $\Leftrightarrow \alpha = 8$

TEST FOR CONSERVATIVE VECTOR FIELD IN THE PLANE

Example Decide whether the vector field is conservative.

a)
$$\mathbf{F}(x, y) = \underbrace{x^2 y \mathbf{i}}_{M} + \underbrace{xy \mathbf{j}}_{N}$$

$$\frac{\partial M}{\partial y} = x^2 \neq \frac{\partial N}{\partial x} = y$$

F is not conservative.

b)
$$\mathbf{F}(x, y) = \underbrace{2x}_{M} \mathbf{i} + \underbrace{y}_{N} \mathbf{j}$$

$$\frac{\partial M}{\partial y} = 0 \quad = \quad \frac{\partial N}{\partial x} = 0$$

F is conservative.

FINDING A POTENTIAL FUNCTION FOR F(x, y)

Find a potential function for $\mathbf{F}(x, y) = 2xy \mathbf{i} + (x^2 - y) \mathbf{j}$. Example N There exists f(x, y) such that $\mathbf{F} = \nabla f$. $\frac{\partial M}{\partial v} = 2x = \frac{\partial N}{\partial x} = 2x$ $2xy \mathbf{i} + (x^2 - y) \mathbf{j} = f_x \mathbf{i} + f_y \mathbf{j}$ $f_x = 2xy \Rightarrow f = \int 2xy \, dx = x^2y + g(y)$ \therefore F is conservative. $f_v = x^2 - y \Rightarrow x^2 + g'(y) = x^2 - y$ $\Rightarrow q'(v) = -v$ $\Rightarrow g(y) = -\frac{1}{2}y^2 + c$ $\therefore f(x,y) = x^2y - \frac{1}{2}y^2 + c$

THE ∇ OPERATOR

- The symbol ∇ that appears in the gradient expression ∇f has not been given a meaning of its own.
- It is often convenient to view ∇ as an operator.

$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j}$$
 Plane
$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}$$
 Space

• We call it the **del operator**.

DIVERGENCE AND CURL

• We will now define two important operations on vector fields: the

divergence and the curl of the field.

- These names originate in the study of **fluid flow**.
- Although we will focus only on their computation, seeing their

physical meaning before is convenient.

DIVERGENCE AND CURL

The **divergence** relates to the way in which fluid flows toward or away from a point.

The field acting like a **source**. $\operatorname{div} \mathbf{F}(x, y) > 0$ The field acting like a **sink**. $\operatorname{div} \mathbf{F}(x, y) < 0$

Slow flow in Fast flow out

 $\operatorname{div} \mathbf{F}(x, y) > 0$



Fast flow in Slow flow out

 $\operatorname{div} \mathbf{F}(x, y) < 0$

DIVERGENCE AND CURL

The **curl** relates to the rotational properties of the fluid at a point.





Clockwise Rotation Curl F(x, y) is negative Counter-Clockwise Rotation Curl F(x, y) is positive

The curl of
$$\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k}$$
 is
curl $\mathbf{F}(x, y, z) = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}$

$$= \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}\right)\mathbf{i} - \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z}\right)\mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right)\mathbf{k}$$

k

The curl of
$$\mathbf{F}(x, y) = M(x, y)\mathbf{i} + N(x, y)\mathbf{j}$$
 is
curl $\mathbf{F}(x, y) = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & 0 \end{vmatrix}$
 $= 0 \mathbf{i} - 0 \mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right) \mathbf{k} = \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right) \mathbf{k}$





Example Find curl **F** of the vector field $\mathbf{F}(x, y, z) = 2xy \mathbf{i} + (x^2 + z^2) \mathbf{j} + (2yz) \mathbf{k}$

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xy & x^2 + z^2 & 2yz \end{vmatrix}$$
$$= (2z - 2z)\mathbf{i} - (0 - 0)\mathbf{j} + (2x - 2x)\mathbf{k}$$
$$= \mathbf{0}$$

TEST FOR CONSERVATIVE VECTOR FIELD IN SPACE

Suppose that M, N, and P have continuous first partial derivatives in an open sphere Q in space. The vector field $\mathbf{F}(x, y, z) = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$ is conservative if and only if curl $\mathbf{F} = \mathbf{0}$.

$$\left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \mathbf{i} - \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \mathbf{k} = \mathbf{0}$$
$$\frac{\partial P}{\partial y} = \frac{\partial N}{\partial z} \quad , \quad \frac{\partial P}{\partial x} = \frac{\partial M}{\partial z} \quad , \quad \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

Example The vector field $\mathbf{F}(x, y, z) = 2xy \mathbf{i} + (x^2 + z^2) \mathbf{j} + (2yz) \mathbf{k}$ in the previous example is conservative because curl $\mathbf{F} = \mathbf{0}$.

TEST FOR CONSERVATIVE VECTOR FIELD IN SPACE



∴ F is not conservative

FINDING A POTENTIAL FUNCTION FOR F(x, y, z)

Example Find a potential function

$$\mathbf{F}(x, y, z) = \frac{2xy}{f_x} \mathbf{i} + \frac{(x^2 + z^2)}{f_y} \mathbf{j} + 2yz \mathbf{k}$$

From previous example, you know that the vector field is conservative. If f(x, y, z) is a function such that $\mathbf{F} = \nabla f$, then

$$f_x = 2xy \Rightarrow f = \int 2xy \, dx = x^2y + g(y, z)$$

But $f_y = x^2 + z^2 \Rightarrow x^2 + g_y(y, z) = x^2 + z^2$
 $\Rightarrow g(y, z) = \int z^2 dy = z^2y + K(z)$
 $\therefore f = x^2y + z^2y + K(z)$

FINDING A POTENTIAL FUNCTION FOR F(x, y, z)

Example Find a potential function $F(x, y, z) = 2xy i + (x^{2} + z^{2}) j + 2yz k$ f_{z} From previous example, you know that the vector field given by is

conservative. If f(x, y, z) is a function such that $\mathbf{F} = \nabla f$, then

$$f = x^{2}y + z^{2}y + K(z)$$

$$f_{z} = 2yz \implies 2yz + K'(z) = 2yz \implies K'(z) = 0 \implies K(z) = c$$

$$\therefore f(x, y, z) = x^{2}y + z^{2}y + c$$

DIVERGENCE OF A VECTOR FIELD

• The **divergence** of $\mathbf{F}(x, y) = M \mathbf{i} + N \mathbf{j}$ in the plane is

div
$$\mathbf{F} = \nabla \cdot \mathbf{F}(x, y) = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

• The divergence of $\mathbf{F}(x, y, z) = M \mathbf{i} + N \mathbf{j} + P \mathbf{k}$ in the space is

div
$$\mathbf{F} = \nabla \cdot \mathbf{F}(x, y, z) = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$$

DIVERGENCE OF A VECTOR FIELD

Example Find the divergence at the point (2,1,-1) for the vector field $\mathbf{F}(x,y,z) = x^3y^2z \,\mathbf{i} + x^2z \,\mathbf{j} + x^2y \,\mathbf{k}$

div
$$\mathbf{F} = \frac{\partial}{\partial x} (x^3 y^2 z) + \frac{\partial}{\partial y} (x^2 z) + \frac{\partial}{\partial z} (x^2 y) = 3x^2 y^2 z$$

div $\mathbf{F}(2,1,-1) = -12$

Theorem If $\mathbf{F}(x, y, z) = M \mathbf{i} + N \mathbf{j} + P \mathbf{k}$ is a vector field and M, N, and P have continuous second partial derivatives, then $\operatorname{div}(\operatorname{curl} \mathbf{F}) = 0$

EQUIVALENT STATEMENTS



Course: Calculus (4)

Chapter: [15] TOPICS IN VECTOR CALCULUS

Section: [15.2] LINE INTEGRALS

PARAMETRIC CURVES IN 3 - SPACE

A space curve C is the set of all ordered triples (x, y, z) together with their defining parametric equations

$$x = f(t), y = g(t) \text{ and } z = h(t)$$

Example The Circular Helix

$$x = 10 \cos t$$
$$y = 10 \sin t$$
$$z = t$$

 $\mathbf{r}(t) = 10 \cos t \,\mathbf{i} + 10 \sin t \,\mathbf{j} + t \mathbf{k}$ $= \langle 10 \cos t \,, 10 \sin t \,, t \rangle$



SMOOTH PARAMETRIZATIONS

- We will say that a curve represented by $\mathbf{r}(t)$ is *smoothly parametrized* by $\mathbf{r}(t)$, or that $\mathbf{r}(t)$ is a smooth function of t if:
 - \checkmark **r**'(*t*) is continuous, and

✓ $\mathbf{r}'(t) \neq \mathbf{0}$ for any allowable value of *t*.

 Geometrically, this means that a smoothly parametrized curve can have no abrupt (مفاجئ) changes in direction as the parameter increases.
Example Determine whether the vector-valued function $\mathbf{r}(t) = t^2 \mathbf{i} + t^3 \mathbf{j}$ is smooth.

 $\mathbf{r}'(t) = 2t\mathbf{i} + 3t^2\mathbf{j}$

✓ The components are continuous functions, and

- ✓ they are both equal to zero if t = 0.
- ✓ So, $\mathbf{r}(t)$ is NOT a smooth function at t = 0.



PIECEWISE SMOOTH PARAMETRIZATION

A curve *C* is **piecewise smooth** when the interval [a, b] can be partitioned into a finite number of subintervals, on each of which *C* is smooth.



PIECEWISE SMOOTH PARAMETRIZATION

Example Find a piecewise smooth parametrization of the graph of *C* shown in the figure.



ARC LENGTH FROM THE VECTOR VIEWPOINT

If C is the graph of a smooth vector-valued function $\mathbf{r}(t)$, then its arc length ℓ from t = a to t = b is

$$\ell = \int_{a}^{b} \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$ from t = 0 to $t = \pi$.

ARC LENGTH FROM THE VECTOR VIEWPOINT

$$\ell = \int_{a}^{b} \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Example Find the arc length of that portion of the circular helix $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$ from t = 0 to $t = \pi$.

$$\mathbf{r}'(t) = \langle -\sin t, \cos t, 1 \rangle \qquad \qquad \ell = \int_{0}^{\pi} ||\mathbf{r}'(t)|| dt$$
$$||\mathbf{r}'(t)|| = \sqrt{(-\sin t)^2 + \cos^2 t + 1} \qquad \qquad = \int_{0}^{\pi} \sqrt{2} dt$$
$$= \sqrt{2} \qquad \qquad \qquad = \sqrt{2} \pi$$

LINE INTEGRALS

 $\int_{a}^{b} f(x) dx \quad \text{Integrate over interval } [a, b]$

f(x,y) ds Integrate over a piecewise
smooth curve C
Line (Curve) Integral



To evaluate a line integral over a plane curve C given by $\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j}$ use the fact that

$$ds = \|\mathbf{r}'(t)\|dt = \sqrt{(x'(t))^2 + (y'(t))^2} dt$$

The arc length of C between points P_{k-1} and P_k is given by

$$\Delta s_k = \int_{t_{k-1}}^{t_k} \|\mathbf{r}'(t)\| \, dt = \|r'(t_k^*)\| \, \Delta t_k$$



Therefore, if *C* is smoothly parametrized by $\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j}$; $t \in [a, b]$

then

$$\int_{C} f(x,y) \, ds = \int_{a}^{b} f(x(t), y(t)) \|\mathbf{r}'(t)\| \, dt$$
$$= \int_{a}^{b} f(x(t), y(t)) \sqrt{x'(t)^2 + y'(t)^2} \, dt$$

Similarly, if C is a curve in 3 –space that is smoothly parametrized by $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$; $t \in [a, b]$

then

$$\int_{C} f(x, y, z) \, ds = \int_{a}^{b} f(x(t), y(t), z(t)) \, \|\mathbf{r}'(t)\| \, dt$$
$$= \int_{a}^{b} f(x(t), y(t), z(t)) \, \sqrt{(x'(t))^{2} + (y'(t))^{2} + (z(t))^{2}} \, dt$$
Note:
$$\int_{C} 1 \, ds = \int_{a}^{b} \|\mathbf{r}'(t)\| \, dt = \text{length of the curve } C$$

Example Using the given parametrization, evaluate the line 2 integral $\int_C (1 + xy^2) ds$ $C = (1 - t)(1,2) + t(0,0) \qquad t \in [0,1]$ = (1 - t, 2 - 2t) + (0, 0)x(t) = 1 - t= (1 - t, 2 - 2t)v(t) = 2 - 2t $\mathbf{r}(t) = (1-t)\mathbf{i} + (2-2t)\mathbf{j}$ $\mathbf{r}'(t) = -\mathbf{i} - 2\mathbf{j}$ $\|\mathbf{r}'(t)\| = \sqrt{5}$

Example Using the given parametrization, evaluate the line integral $\int_C (1 + xy^2) ds$

▲ У

2

(1, 2)

x(t) = 1 - t

y(t) = 2 - 2t

 $t \in [0,1]$

$$\int_{C} (1 + xy^{2}) ds = \int_{0}^{1} (1 + (1 - t)(2 - 2t)^{2}) ||\mathbf{r}'(t)|| dt \qquad \begin{aligned} x(t) &= 1 - \\ y(t) &= 2 - \\ &= \int_{0}^{1} (1 + 4(1 - t)^{3})\sqrt{5} dt \qquad \qquad \\ &= 2\sqrt{5} \end{aligned}$$

Example Using the given parametrization, evaluate the line integral $\int_{C} (1 + xy^2) ds$

$$C = (1 - t)(0,0) + t(1,2) = (t,2t) \qquad t \in [0,1]$$

$$\mathbf{r}(t) = t \,\mathbf{i} + 2t \,\mathbf{j}$$
 $\mathbf{r}'(t) = \mathbf{i} + 2\mathbf{j}$ $\|\mathbf{r}'(t)\| = \sqrt{5}$

$$\int_{C} (1 + xy^2) \, ds = \int_{0}^{1} (1 + 4t^3) \|\mathbf{r}'(t)\| \, dt$$
$$= \int_{0}^{1} (1 + 4t^3) \sqrt{5} \, dt = 2\sqrt{5}$$



- **NOTE** The integrals in the previous example agree, even though the corresponding parametrizations of *C* have opposite orientations.
 - This illustrates the important result that the value of a line integral of *f* with respect to *s* along *C* does not depend on the parametrization of the line segment *C*; any smooth parametrization will produce the same value.
 - Later in this section we will see that for line integrals of vector functions, the orientation of the curve is important.

Example Evaluate the line integral $\int_C (xy + z^3) ds$ from π (1,0,0) to $(-1,0,\pi)$ along the helix C that is represented by the parametric equations Z. $x = \cos t$ $y = \sin t$ z = t $t \in [0, \pi]$ 0 (1, 0, 0) $\mathbf{r}(t) = \cos t \, \mathbf{i} + \sin t \, \mathbf{j} + t \, \mathbf{k}$ $\mathbf{r}'(t) = -\sin t \, \mathbf{i} + \cos t \, \mathbf{j} + \mathbf{k}$ $\|\mathbf{r}'(t)\| = \sqrt{(-\sin t)^2 + (\cos t)^2 + (1)^2} = \sqrt{2}$ $\int (xy + z^3) ds = \int (\cos t \sin t + t^3) \sqrt{2} dt = \frac{\sqrt{2} \pi^4}{4}$



Let *C* be a path composed of smooth curves C_1, C_2, \dots, C_n . If *f* is continuous on *C*, then it can be shown that

$$\int_{C} f(x,y)ds = \int_{C_{1}} f(x,y)ds + \int_{C_{2}} f(x,y)ds + \dots + \int_{C_{n}} f(x,y)ds$$

Example Evaluate $\int_{C} xds$ where C is the piecewis
smooth curve shown in the figure.
 C_{1} : $x = t$ $y = t$ $t \in [0,1]$
 C_{2} : $x = 1 - t$ $y = (1 - t)^{2}$ $t \in [0,1]$
(0,0)

Example Evaluate $\int_C x ds$ where *C* is the piecewis smooth curve shown in the figure.

$$C_1: \quad x = t \quad y = t \quad t \in [0,1]$$

$$\int_{C_1} x ds = \int_{0}^{1} t \sqrt{2} dt = \frac{1}{\sqrt{2}}$$



 $\|\mathbf{r}'(t)\| = \sqrt{2}$

Example Evaluate $\int_C x ds$ where *C* is the piecewis smooth curve shown in the figure.

C₁:
$$x = t$$
 $y = t$ $t \in [0,1]$
C₂: $x = 1 - t$ $y = (1 - t)^2$ $t \in [0,1]$

y

$$C = C_1 + C_2$$

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 $\mathbf{r}(t) = (1-t)\mathbf{i} + (1-t)^2\mathbf{j}$

 $\|\mathbf{r}'(t)\| = \sqrt{1 + 4(1-t)^2}$

r'(t) = -i - 2(1-t)i

$$\int_{C_2} x ds = \int_0^1 (1-t)\sqrt{1+4(1-t)^2} dt$$

$$\Rightarrow = -\frac{1}{8} \int_5^1 \sqrt{u} \, du = \frac{1}{12} \left(5\sqrt{5}-1\right)$$
Let
$$u = 1 + 4(1-t)^2$$

Example Evaluate $\int_C x ds$ where *C* is the piecewis smooth curve shown in the figure.

C₁:
$$x = t$$
 $y = t$ $t \in [0,1]$
C₂: $x = 1 - t$ $y = (1 - t)^2$ $t \in [0,1]$



$$\therefore \int_{C} x ds = \int_{C_1} x ds + \int_{C_2} x ds$$

$$=\frac{1}{\sqrt{2}}+\frac{1}{12}(5\sqrt{5}-1)$$

LINE INTEGRALS OF VECTOR FIELDS

- We can also consider integrating a vector field over a curve in the plane.
- One of the most important physical applications of line integrals is how to determine the work done by F in moving a particle along a curve C.
- The work W done by a constant force of magnitude F on a point that moves a distance d in a straight line in the direction of the force is W = F d.

LINE INTEGRALS OF VECTOR FIELDS

- Consider a force field F(x, y) and a piecewise continuous smooth curve **C**.
- We wish to compute the work done by this force in moving a particle along a smooth curve **C**.
- We divide **C** into sub-arcs with lengths Δs_i .
- To determine the work done by the force, you need consider only that part of the force that is acting in the same direction as that in which the object is, T(t).



LINE INTEGRALS OF VECTOR FIELDS

We call $\mathbf{T}(t)$ the **unit tangent** vector to \mathbf{C} at t, where $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$

This means that at each point on C, you can consider the projection of the force vector \mathbf{F} onto the unit tangent vector \mathbf{T} .





Let **F** be a continuous vector field defined on a smooth curve *C* given by $\mathbf{r}(t)$ where $a \le t \le b$.



Example Find the work done by the force field

$$\mathbf{F}(x, y, z) = -\frac{1}{2}x\mathbf{i} - \frac{1}{2}y\mathbf{j} + \frac{1}{4}\mathbf{k}$$

on a particle as it moves from the point (1,0,0) to (-1,0,3 π)
along the helix given by $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + t \mathbf{k}$.





Find the work done by the force field Example $\mathbf{F}(x, y, z) = -\frac{1}{2}x\mathbf{i} - \frac{1}{2}y\mathbf{j} + \frac{1}{4}\mathbf{k}$ on a particle as it moves from the point (1,0,0) to $(-1,0,3\pi)$ along the helix given by $\mathbf{r}(t) = \cos t \, \mathbf{i} + \sin t \, \mathbf{j} + t \, \mathbf{k}$. $t = 3\pi$ $(-1, 0, 3\pi)$ $\int \mathbf{F} \cdot d\mathbf{r} = \int \left(-\frac{1}{2} \cos t \, , -\frac{1}{2} \sin t \, , \frac{1}{4} \right) \cdot \langle -\sin t \, , \cos t \, , 1 \rangle \, dt$ 3π- $=\int \frac{1}{4}dt = \frac{3\pi}{4}$ (1, 0, 0)

- **NOTE** For line integrals of vector functions, the orientation of the curve *C* is important.
 - If the orientation of the curve is reversed, the unit tangent vector $\mathbf{T}(t)$ is changed to $-\mathbf{T}(t)$, and you obtain

$$\int_{-C} \mathbf{F} \cdot d\mathbf{r} = -\int_{C} \mathbf{F} \cdot d\mathbf{r}$$

Example Let $\mathbf{F}(x, y) = y \mathbf{i} + x^2 \mathbf{j}$. Evaluate the line integral $\int_C \mathbf{F} \cdot d\mathbf{r}$ for each parabolic curve shown in the figure. $C_1: \mathbf{r}_1(t) = (4-t)\mathbf{i} + (4t-t^2)\mathbf{j} \quad 0 \le t \le 3$ $\int_{\Omega} \mathbf{F} \cdot d\mathbf{r}_1 = \int_{\Omega} \mathbf{F}(x(t), y(t)) \cdot \mathbf{r}_1'(t) dt$ $= \int \left((4t - t^2)\mathbf{i} + (4 - t)^2 \mathbf{j} \right) \cdot (-\mathbf{i} + (4 - 2t)\mathbf{j}) dt$ $= \int (-2t^3 + 21t^2 - 68t + 64) dt = \frac{69}{2}$

Example Let $\mathbf{F}(x, y) = y \mathbf{i} + x^2 \mathbf{j}$. Evaluate the line integral $\int_{C} \mathbf{F} \cdot d\mathbf{r}$ for each parabolic curve shown in the figure. 2 C_2 : $\mathbf{r}_2(t) = t\mathbf{i} + (4t - t^2)\mathbf{j}$ $1 \le t \le 4$ $\int_{C_2} \mathbf{F} \cdot d\mathbf{r}_2 = \int_{C_2}^{4} \mathbf{F}(x(t), y(t)) \cdot \mathbf{r}'_2(t) dt$

$$\int_{1}^{4} ((4t - t^{2})\mathbf{i} + t^{2}\mathbf{j}) \cdot (\mathbf{i} + (4 - 2t)\mathbf{j}) dt$$

$$= \int_{1}^{4} (-2t^{3} + 3t^{2} + 4t) dt = -\frac{69}{2}$$

LINE INTEGRALS IN DIFFERENTIAL FORM

- A second commonly used form of line integrals is derived from the vector field notation used in Section 15.1.
- If **F** is a vector field of the form $\mathbf{F}(x, y) = M\mathbf{i} + N\mathbf{j}$, and *C* is given by $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$, then $\mathbf{F} \cdot d\mathbf{r}$ is often written as Mdx + Ndy.

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{C} \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} dt = \int_{C} (M\mathbf{i} + N\mathbf{j}) \cdot (x'(t)\mathbf{i} + y'(t)\mathbf{j}) dt$$

$$= \int_{C} \left(M \frac{dx}{dt} + N \frac{dy}{dt} \right) dt = \int_{C} \left(M dx + N dy \right)$$

Evaluate $\int_{C} (ydx + x^2dy)$ where C is the parabolic arc given Example by $y = 4x - x^2$ from (4,0) to (1,3) as shown in the figure. dy = (4 - 2x)dx*C*: $y = 4x - x^2$ $\int_{\Omega} (ydx + x^2dy) = \int_{\Omega} (4x - x^2)dx + x^2(4 - 2x)dx$ 2 - $=\int (4x+3x^2-2x^3)dx$ (4, 0)

Example Evaluate $\int_C x^2 y dx + x dy$ where C is the triangular path shown in the figure.

$$C_{1}: \text{From } (0,0) \text{ to } (1,0) \qquad y = 0 \qquad dy = 0$$
$$\int_{C_{1}}^{1} x^{2}y dx + x dy = \int_{0}^{1} 0 dx = 0$$



C₂: From (1,0) to (1,2)
$$x = 1$$
 $dx = 0$
$$\int_{C_2} x^2 y dx + x dy = \int_{0}^{2} 1 dy = 2$$

Example Evaluate $\int_C x^2 y dx + x dy$ where *C* is the triangular path shown in the figure.

$$C_{3}: \text{From (1,2) to (0,0)} \qquad y = 2x \quad dy = 2dx$$

$$\int_{C_{3}}^{0} x^{2}ydx + xdy = \int_{1}^{0} x^{2}(2x)dx + x(2dx)$$

$$= \int_{1}^{0} (2x^{3} + 2x)dx = -\frac{3}{2}$$

$$\therefore \int_{C} x^{2}ydx + xdy = 0 + 2 - \frac{3}{2} = \frac{1}{2}$$



$$C_{1}: \quad x = t \quad dx = dt \qquad y = 0 \quad dy = 0$$

$$\int_{C_{1}} x^{2}y dx + x dy = \int_{0}^{1} (t^{2})(0)(dt) + (t)(0) = 0$$

$$C_{2}: \quad x = 1 \quad dx = 0 \qquad y = 2t \quad dy = 2dt$$

$$\int_{C_{2}} x^{2}ydx + xdy = \int_{0}^{1} (1^{2})(2t)(0) + (1)(2dt) = 2$$

$$O \quad C_{1} \quad A(1, 0)$$

$$C_{3}: x = 1 - t \quad dx = -dt \quad y = 2 - 2t \quad dy = -2dt \quad y = -2dt$$


Course: Calculus (4)

<u>Chapter: [15]</u> TOPICS IN VECTOR CALCULUS

Section: [15.3] INDEPENDENCE OF PATH; CONSERVATIVE VECTOR FIELDS

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

$$\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \end{array} \\ C_{1} = (1-t)(0,0) + t(1,1) = (t,t) \\ r_{1}(t) = ti + tj \\ \end{array} \\ \int_{1}^{1} \mathbf{r}_{1}(t) = ti + tj \\ \end{array} \\ \begin{array}{c} \int_{1}^{1} \mathbf{F} \cdot d\mathbf{r}_{1} = \int_{0}^{1} \mathbf{F} (x(t), y(t)) \cdot \mathbf{r}_{1}'(t) dt \\ = \int_{0}^{1} \left\langle \frac{1}{2}t^{2}, \frac{1}{4}t^{2} \right\rangle \cdot \langle 1,1 \rangle dt = \int_{0}^{1} \frac{3}{4}t^{2} dt = \frac{1}{4} \end{array}$$

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

(2)
$$C_2: x = y^2 \quad dx = 2ydy$$

$$\int_{C_2} Mdx + Ndy = \int_{0}^{1} \frac{1}{2}xydx + \frac{1}{4}x^2dy$$

$$= \int_{0}^{1} \frac{1}{2}(y^2)(y)(2ydy) + \frac{1}{4}(y^4)dy = \int_{0}^{1} \frac{5}{4}y^4dy$$

$$= \int_{0}^{1} \frac{1}{2}(y^2)(y)(2ydy) + \frac{1}{4}(y^4)dy = \int_{0}^{1} \frac{5}{4}y^4dy$$

$$= \frac{1}{4}$$

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

(3)
$$C_3: y = x^3 \quad dy = 3x^2 dx$$

$$\int_{C_3} M dx + N dy = \int_0^1 \frac{1}{2} xy dx + \frac{1}{4} x^2 dy$$

$$= \int_0^1 \frac{1}{2} (x) (x^3) (dx) + \frac{1}{4} (x^2) (3x^2 dx) = \int_0^1 \frac{5}{4} x^4 dx$$

$$= \frac{1}{4}$$

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

Note that the force field
$$\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$$
 is conservative.
 $M = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ is conservative.
 $\frac{\partial M}{\partial y} = \frac{x}{2} = \frac{\partial N}{\partial x}$

So, the work done by the conservative vector field ${\bf F}$ is the same for each path.

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

Since the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ is conservative, then $\mathbf{F} = \nabla f = \langle f_x, f_y \rangle$ M N $=\langle M,N\rangle$ $f_y = N = \frac{1}{4}x^2$ $f = \int \frac{1}{4}x^2 dy = \frac{1}{4}x^2y + g(x)$ $\frac{1}{2}xy + g'(x) = \frac{1}{2}xy \qquad \begin{array}{l} g'(x) = 0\\ g(x) = c \end{array}$ $f_{\gamma} = M$

Example Find the work done by the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ on a particle that moves from (0,0) to (1,1) along each path, as shown in the figures.

Since the force field $\mathbf{F}(x, y) = \frac{1}{2}xy\mathbf{i} + \frac{1}{4}x^2\mathbf{j}$ is conservative, then $\mathbf{F} = \nabla f = \langle f_x, f_y \rangle$ $f(x, y) = \frac{1}{4}x^2y + c$ Potential Function

Question: What is the value of f(1, 1) - f(0, 0)?

$$= \left[\frac{1}{4}(1^2)(1) + c\right] - \left[\frac{1}{4}(0^2)(0) + c\right] = \frac{1}{4}$$

Let C be a piecewise smooth curve lying in an open region R and given

by

$$\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$$
, $a \le t \le b$

If $\mathbf{F}(x, y) = M\mathbf{i} + N\mathbf{j}$ is conservative in R, and M and N are continuous in R, then

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{C} \nabla f \cdot d\mathbf{r} = f(x(b), y(b)) - f(x(a), y(a))$$

where f is a potential function of **F**. That is, $\mathbf{F}(x, y) = \nabla f(x, y)$.

Example Evaluate
$$\int_C \mathbf{F} \cdot d\mathbf{r}$$
 where C is a piecewise
smooth curve from $(-1,4)$ to $(1,2)$ as shown
in the figure, and
 $\mathbf{F}(x,y) = 2xy \mathbf{i} + (x^2 - y) \mathbf{j}$
F is conservative
 $f(x,y) = x^2y - \frac{1}{2}y^2 + c$
 $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \nabla f \cdot d\mathbf{r} = f(1,2) - f(-1,4)$
 $= 0 - (-4) = 4$

Example Evaluate
$$\int_{C} \mathbf{F} \cdot d\mathbf{r}$$
 where *C* is a piecewise
smooth curve from (-1,4) to (1,2) as shown
in the figure, and
 $\mathbf{F}(x, y) = 2xy \mathbf{i} + (x^{2} - y) \mathbf{j}$
*C**: $\mathbf{r}(t) = (2t - 1)\mathbf{i} + (4 - 2t)\mathbf{j}$ $t \in [0,1]$
 $\mathbf{r}'(t) = 2\mathbf{i} - 2\mathbf{j}$
 $\mathbf{F}(x(t), y(t)) = 2(2t - 1)(4 - 2t)\mathbf{i} + ((2t - 1)^{2} - (4 - 2t))\mathbf{j}$
 $= (-8t^{2} + 20t - 8)\mathbf{i} + (4t^{2} - 2t - 3)\mathbf{j}$
 $\mathbf{F} \cdot d\mathbf{r} = \mathbf{F} \cdot \mathbf{r}'(t)dt = -24t^{2} + 44t - 10$
F is conservative



INDEPENDENCE OF PATH

A region in the plane (or in space) is **connected** when any two points in the region can be joined by a piecewise smooth curve lying entirely within the region.

If \mathbf{F} is continuous on an open connected region, then the line integral

$$\int_{C} \mathbf{F} \cdot d\mathbf{r}$$

is independent of path if and only if ${\bf F}$ is conservative.



EQUIVALENT STATEMENTS



ORIENTATION AND PARAMETRIZATION OF A CURVE

Example We have seen that

$$\int_{C} x^{2}ydx + xdy = \frac{1}{2} \neq 0$$

where *C* is the triangular path shown in
the figure.

 $\therefore \mathbf{F} = x^2 y \mathbf{i} + x \mathbf{j}$ is not conservative is not independent of path



Course: Calculus (4)

<u>Chapter: [15]</u> TOPICS IN VECTOR CALCULUS

Section: [15.4] GREEN'S THEOREM

SIMPLE CURVES

- A curve C given by $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ where $a \le t \le b$, is simple when it does not cross itself between its endpoints.
- A simple parametric curve may or may not be **closed**.



SIMPLY CONNECTED REGION

or holes.

- A connected plane region *R* is **simply connected** when every simple closed curve in *R* encloses only points that are in *R*.
- Informally, a simply connected region cannot consist of *separate parts*



Simply connected

Let R be a simply connected region with a piecewise smooth boundary C, oriented counterclockwise. If M and N have continuous first partial derivatives in an open region containing R, then

$$\oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right) dA$$

This theorem states that the value of a double integral over a simply connected plane region R is determined by the value of a line integral around the boundary of R.

An integral sign with a circle is sometimes used to indicate a line integral around a simple closed curve.

To indicate the orientation of the boundary, an arrow can be used.



Example Use Green's Theorem to evaluate the line integral

$$\oint_C y^3 dx + (x^3 + 3xy^2) dy$$

where *C* is the path from (0,0) to (1,1) along the graph of $y = x^3$
and from (1,1) to (0,0) along the graph of $y = x$ as shown in the

and from (1,1) to (0,0) along the graph of y = x as show figure. $C = C_1 + C_2$

$$M = y^{3}$$

$$N = x^{3} + 3xy^{2}$$

$$M = y^{3}i + (x^{3} + 3xy^{2})j$$

$$Not Conservative$$

$$M = y^{3} + 3xy^{2}$$

$$Not Conservative$$

$$\int_{(0,0)}^{1} \frac{y = x^{3}}{y = x^{3}}$$

Example

$$\oint_C y^3 dx + (x^3 + 3xy^2) dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right) dA$$

y

$$C = C_1 + C_2$$
 Type I
1
 $y = x$
 C_1
 C_1
 C_2
 $y = x^3$
 $(0, 0)$
 1

 $M = y^3$ $N = x^3 + 3xy^2$

$$= \iint_{R} (3x^{2} + 3y^{2} - 3y^{2}) dA$$
$$= \iint_{R} 3x^{2} dA = \int_{0}^{1} \int_{x^{3}}^{x} 3x^{2} dy dx = \frac{1}{4}$$

Example Evaluate

$$\oint_C (\tan^{-1} x + y^2) dx + (e^y - x^2) dy$$

where *C* is the path shown in the figure.



$$M = \tan^{-1} x + y^{2} \qquad \Rightarrow \mathbf{F} = (\tan^{-1} x + y^{2})\mathbf{i} + (e^{y} - x^{2})\mathbf{j}$$
$$N = e^{y} - x^{2} \qquad \qquad \text{Not Conservative}$$
$$\frac{\partial M}{\partial y} = 2y \neq \frac{\partial N}{\partial x} = -2x$$

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 $=-\frac{1}{3}$

Example

Example

$$\oint_{C} (\tan^{-1}x + y^{2})dx + (e^{y} - x^{2})dy = \iint_{R} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right) dA = \int_{(-3,0)}^{0} \int_{(-1,0)}^{0} \int_{(1,0)}^{0} \int_{(3,0)}^{0} \int_{(-1,0)}^{0} \int_{(-1,0)}^{0$$

LINE INTEGRAL FOR AREA

Another application of Green's Theorem is in computing areas.

Area of
$$R = \iint_{R} 1 \, dA$$

$$= \iint_{R} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \, dA$$
For example, let $\frac{\partial M}{\partial y} = 0$
 $M = c(x) = 0$
 $= \oint_{C} M \, dx + N \, dy$
Then $\frac{\partial N}{\partial x} = 1$
 $N = x$

y

R

C

LINE INTEGRAL FOR AREA

If R is a plane region bounded by a piecewise smooth simple closed curve C oriented counterclockwise, then the area of R is given by

$$A = \oint_{C} x dy$$
$$= \oint_{C} -y dx$$
$$= \frac{1}{2} \oint_{C} x dy - y dx$$



LINE INTEGRAL FOR AREA

Example Use a line integral to find the area of the ellipse

 $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

C:
$$x = a \cos t$$
 $y = b \sin t$ $0 \le t \le 2\pi$

$$A = \oint_C x dy = \int_0^{2\pi} (a \cos t) (b \cos t dt)$$
$$= \frac{ab}{2} \int_0^{2\pi} (1 + \cos(2t)) dt = ab\pi$$

