Outline of the Lecture
> Image Types
$>$ Converting between data classes and image types
$>$ Converting images using IPT Function
$>$ Matlab image Arithmetic Functions
> Array indexing

## Image Types

- The toolbox supports four types of images:
- Intensity Image.
- Binary Images.
- Indexed Images.
- RGB Images.

Intensity Images: (Gray scale Images)

- An intensity image is a data matrix whose values have been scaled to represent intensities.

| Allowed Classes | Range |
| :--- | :--- |
| uint8 | $0-255$ |
| uint16 | $0-65535$ |
| double | $[0-1]$ |



- Logical array containing only $\mathbf{0 s}$ and $\mathbf{1 s}$, interpreted as black and white, respectively. In matlab, by convention, BW is a variable Binary image.



## Binary Images

- If the array contains 0 s and 1 s whose values are of data class different from logical (for example uint8), it is not considered a binary image in Matlab.


## Conversion a numeric array to binary:

1. To convert, we use function logical.
```
>> x = [ llllllll}
>> y = logical (x);
```

If $\mathbf{x}$ contains other than $0 \boldsymbol{s}$ and $1 \mathbf{s}$, the logical function converts all nonzero values to logical 1s.
2. Using relational and logical operators we can create a logical array.

- To test if an array is logical, we use islogical function:
>> islogical (y); \% returns 1 if y is a logical array; otherwise it returns 0;
- logical array can be converted to numeric arrays using the data class conversion functions.


## Indexed Image

- An indexed image consists of an array and a colormap matrix.
- The pixel values in an array are direct indices into a colormap.
- Each pixel has a value which does not give its color (as for an RGB image), but an index to the color in the map.

- Variable X refer to array, variable map refer to the colormap.
$>$ The array of class logical, uint8, uint16, single or double.
$>$ The colormap matrix is an m -by-3 array of class double (values in [0lll 01$]$ range).
$>$ Each row of map specifies the red, green and blue components of a single color.
$>$ The color of each image pixel is determined by using corresponding value of X as an index into map.
$>$ A colormap is often stored with an indexed image and is automatically loaded with image when using imread function.

| Relationship between values in the image matrix and the colormap |  |
| :--- | :--- |
| class | Range of colormap |
| single, double | 1 through p, p is the length of the colormap, <br> Value 1- first row, 2 second, etc |
| logical, uint8 or uint16 | value 0 points to the first row, value 1 points <br> to the second, and so on |

RGB color Image (true color image)

- True color images, require a three-dimensional array (m-by-n-by-3) of class uint8, uint16, single or double whose pixel values specify intensity values.

| class | range |
| :--- | :--- |
| single, double | $[0,1]$ |
| uint8 | $[0255]$ |
| uint16 | $[065535]$ |

- Unlike an indexed image, however, these intensity values are stored directly in the image array, not indirectly in a colormap.
- m and n are the numbers of rows and columns of pixels in the image, and the third dimension consists of three planes, containing red, green, and blue intensity values.
- For example: to determine the color of the pixel $(\mathbf{1 1 2 , 8 6})$
- Look at the RGB triplet stored in (112, 86, 1:3). Suppose $(112,86,1)$ contains the value $0.1238,(112,86,2)$ contains 0.9874 and $(112,86,3)$ contains 0.2543
- The color of the pixel at $(112,86)$ is: $0.1238 \quad 0.98740 .2543$


| 49 | 55 | 56 | 57 | 52 | 53 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 58 | 60 | 60 | 58 | 55 | 57 |
| 58 | 58 | 54 | 53 | 55 | 56 |
| 83 | 78 | 72 | 69 | 68 | 69 |
| 88 | 91 | 91 | 84 | 83 | 82 |
| 69 | 76 | 83 | 78 | 76 | 75 |
| 61 | 69 | 73 | 78 | 76 | 76 |


| 64 | 76 | 82 | 79 | 78 | 78 |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 93 | 93 | 91 | 91 | 86 | 86 |
| 88 | 82 | 88 | 90 | 88 | 89 |
| 125 | 119 | 113 | 108 | 111 | 110 |
| 137 | 136 | 132 | 128 | 126 | 120 |
| 105 | 108 | 114 | 114 | 118 | 113 |
| 96 | 103 | 112 | 108 | 111 | 107 |


| 66 | 80 | 77 | 80 | 87 | 77 |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 81 | 93 | 96 | 99 | 86 | 85 |
| 83 | 83 | 91 | 94 | 92 | 88 |
| 135 | 128 | 126 | 112 | 107 | 106 |
| 141 | 129 | 129 | 117 | 115 | 101 |
| 95 | 99 | 109 | 108 | 112 | 109 |
| 84 | 93 | 107 | 101 | 105 | 102 |

- Matlab expects operands in numeric computation to be of double.
- When you store an image, you should store it as uint8 image, since this requires far less memory than double.
- When you are processing an image, you should convert it to double, to convert, we use 2 methods:

1) Type casting
$\checkmark$ Convert from one data type to another: B= data_class_name (A)
Example (1):
>> $B=$ double (A)
Example (2):
>> D = uint8 (c);
D If c is an array of class double, in which all values are $[\mathbf{0} \mathbf{- 2 5 5}$ ] (possible fractional value).
D If an array of class double has any values outside the range [llllle matlab converts to $\mathbf{0}$ all values that are less than $\mathbf{0}$, and converts to $\mathbf{2 5 5}$ all values that are greater than 255.
D Numbers in between are converted to integers by discarding their fractional parts.
$\checkmark$ Converting any of the numeric data classes to logical
D Results in an array with logical 1s in location where the input array has nonzero values and logical 0 s where the input array contains 0 s .
2) Converting between image classes and types.
$\checkmark$ Perform necessary scaling to convert between image classes and types.
a) im2uint8 ( x ) detects input data class and scales to allow recognition of data as valid image data.
Example: Convert an image named x from double to uint8.

- Consider the following $2 * 2$ image f of class double.
>> $f=[-0.5$
$0.5 ; 0.75$
1.5]
- Performing the conversion
>> g= im2uint8 (f)
ans
\% $\quad \mathrm{g}=0 \quad 128$
\% $191 \quad 255$
b) im2double ( x ) converts x input to class double in range [ $\mathbf{0} 1$ 1], unless input is of class double, no effect.
Example: Consider the class uint8 image.
>> h = uint8 ([25 50; 128 200]);
- Performing the conversion
>> g = im2double (h);
ans
$\mathrm{g}=0.0980 \quad 0.1961$
$0.4706 \quad 0.7843$
c) mat2gray ( $\mathrm{x},[$ Amin Amax]) takes arbitrary double array input and scaled to range [01].
D Values < Amin function converts them to zero.
D Values < Amax function converts them to 1.
- Convert an arbitrary array of double to an array of class double scaled to the range [01].
>> mat2gray (x) \% sets the values of Amin and Amax to the actual \%minimum values in x .
d) im2bw ( $\mathrm{x}, \mathrm{T}$ ) converts intensity image (input matrix) to a binary image, anything less than T output set to $\mathbf{0}$, otherwise output set to 1 .
D $\mathrm{T}=[0,1]$
D Output is logical.
>> Im2bw (x) \% T = 0.5 (default).
Example: Convert the following double image $f=\left[\begin{array}{llll}1 & 2 ; & 3 & 4\end{array}\right]$ to binary such that values 1 and 2 become 0 and the other two values become 1.


## Solution:

D First we convert it to the range [01]
>> g= mat2gray (f)

$$
\begin{aligned}
& \text { ans } \\
& \mathrm{g}=0
\end{aligned}
$$

0.66671 .000

D Then we convert it to binary using a threshold (0.6)
>> gb= im2bw (g, 0.6)
ans
$\begin{array}{ll}\mathrm{gb}=0 & 0 \\ & 1\end{array} \quad 1 \begin{aligned} & \text { Converting images using IPT Functions }\end{aligned}$

| Converting images using IPT Functions |  |
| :--- | :--- |
| Matlab Command | operations |
| dither (.) | Gray scale to Binary images. |
|  | RGB to Indexed images. |
| gray2ind (.) | Intensity to indexed images. |
| ind2gray (.) | Indexed to intensity images. |
| ind2rgb ( ) | indexed to RGB images. |
| mat2gray ( ) | Regular matrix to intensity images, create a gray <br> scale intensity image from data in a matrix by <br> scaling the data. |
| rgb2gray () | RGB to intensity images. |
| rgb2ind ( ) | RGB to indexed images. |
| im2bw ( ) | intensity to binary images. |

## Examples:

>> $y=$ ind2gray (x,map) ;
>> [y,map] = gray2ind(x);
>> $y=r g b 2 g r a y(x)$;
>> $y=$ gray2rgb(x);
>> [y,map] = rgb2ind;
>> $y=$ ind2rgb (x,map) ;

## Matlab image Arithmetic Functions

| Matlab image Arithmetic Functions |  |  |
| :--- | :--- | :--- |
| Toolbox (IPT) | Matlab | Description |
| imadd (A,B) | A+B | Adding two images |
| imsubtract (A,B) | A-B | Subtracting two images |
| immultiply (A,B) | A.*B | Multiply two images |
| imdivide (A,B) | A./B | Divide two images (the values are rounded <br> to the nearest integer, not truncated like <br> true integer arithmetic) |

Example: Reading a true color image into Matlab:
>> I = imread ('football jpg');
>> class (I) \% uint8
>> size (I) \% 2503203
>> figure
>> image (I) ;
>> title ('some title');
>> xlabel ('some text');
>> i (231, 100,:)
$\%$ ans $(:,: 1)=48$
$\%$ ans $(:,: 2)=37$
\% ans $(:,:, 3)=41$
>> i= double (i) /255;
>> i $(231,100$, :)
$\%$ ans $(:,:, 1)=0.1882$
$\%$ ans $(:,:, 2)=0.1451$
\%ans (:, :, 3) = 0.1608
>> class (i) \% double

Array indexing
a) vector indexing

## Examples:

$\gg v=\left[\begin{array}{lllll}1 & 3 & 5 & 7 & 9\end{array}\right]$ \% row vector declaration
$\gg v(2)$
$\%$ access the second element of the $v$.
$\gg w=v^{\prime}$
\% row vector is converted to a column vector using
\% the transpose operator (')
>> v(1:3)
\% To access blocks of elements, we use matlab's colon notation.
\% Access first three elements of $v$.
>> v(2:4) \% access the second through the fourth.
>> v(3:end) $\%$ all element from third to the last.
>> v(:) \% produce a column vector.
>> v(1: end) \% produce a row vector.
>> v(1:2:end)
$\%$ start at 1 , count up by 2 and stop when the count reaches the last.
>> v(end:-2:1)
\% started at last, decreased by 2, and stopped at the first element.
b) Matrix indexing:
>> $A=\left[\begin{array}{lllllllll}1 & 2 & 3 ; & 4 & 5 & 6 ; & 7 & 9\end{array}\right] \% 3 * 3$ matrix declaration.
>> $A(2,3) \%$ access element in a matrix (2-row, 3-column).
>> C = A (:, 3) \% (all rows, third columns).
>> $T=A(1: 2,1: 3) \%$ extract the top two rows.
>> A (end, end) \% Get the last element (last row, lost column).
>> $\mathrm{E}=\mathrm{A}$ ([13], [2 3]); \% using vectors to index into a matrix.

