

Philadelphia University Faculty of Engineering

## **Marking Scheme**

Examination Paper Department of CE

## Module: Microprocessors (630371)

First Exam

Second Semester

Date: 10/04/2011

Section 1

Weighting 15% of the module total

Lecturer:

Coordinator:

Internal Examiner:

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## Marking Scheme Microprocessors (630371)

The presented exam questions are organized to overcome course material, the exam contains 5 questions; *all questions* are compulsory requested to be answered. Thus, the student is permitted to answer any question out of the existing ones in this section.

## **Marking Assignments**

The following scheme shows the marks assignments for each question. They show also the steps for which a student can get marks along the related procedure he/she achieves.

**<u>Question 1</u>** This question is attributed with 5 marks if answered properly

The answer for this question as the following:

a)

b)

a)

- 1. What are the names of the 4 segment registers?
  - Data, Index, Code, Stack c) Stack, Extra, Code, Data
  - b) Stack, Data, Base, Counter d) Stack, Index, Extra, Code
- 2. If **DS** = **90A3H**, then the range of physical addresses for the data segment is:
  - 90A30H 9FA30H c) 00000H 090A3H
  - 090A3 190A2H d) 90A30 A0A2FH
- 3. The 8086/8088 used two processing logical units which were known as:
  - a) Segment and Offset Unitsb) Bus Interface Unit and Execution Unit
  - c) Bus Unit and Execution Interface Unit
  - d) ALU and Control Unit
- 4. In the following data definition, assume that List2 begins at offset 2000h. What is the offset of the third value (5)?

			List2 WORD 3,	4,5,6,	7	
	a)	2004h	C	) 200	)2	
	b)	2006	d	) 200	)3	
5.	The EQU directive permits a constant to be redefined at any point in a progra					rogram.
	a)	True	b	) Fal	lse	-

Question 2 This question is attributed with 2.5 marks if answered properly

The answer for this question as the following:

MOV statements	Explain
mov ds,45;	immediate move to DS not permitted
mov esi,wVal;	size mismatch
mov eip,dVal;	EIP cannot be the destination
mov 25,bVal;	immediate value cannot be destination
<pre>mov bVal2,bVal;</pre>	memory-to-memory move not permitted

**<u>Ouestion 3</u>** This question is attributed with 2.5 marks, if answered properly. The answer for this question as the following:

Destination	SF	ZF	CF
AX = 0100h	0	0	0
AX = 00FFh	0	0	0
AL = 00h	0	1	1
BH = 01h	0	0	1
AL = FFh	1	0	1

Question 4 This question is attributed with 2 marks, if answered properly.

The answer for this question as the following:

- 1. General purpose registers (Data Registers)
- 2. Segment Registers
- 3. Index registers
- 4. Status and Control register

**Question 5** This question is attributed with 3 marks, if answered properly. The complete code for this question as the following:

```
TITLE Calculate the expression
.386
.MODEL FLAT
.STACK 4096
.data
  X SDWORD 23
  Y SDWORD 3fceh
  Z SDWORD 42
  R SDWORD ?
.code
                                                 (1.5 marks)
main PROC
  mov ebx,Y
  add ebx,ebx
  neg ebx
  add ebx,Z
  mov eax,X
  sub eax, ebx
  mov R,eax
main ENDP
END main
                                                 (1.5 marks)
```