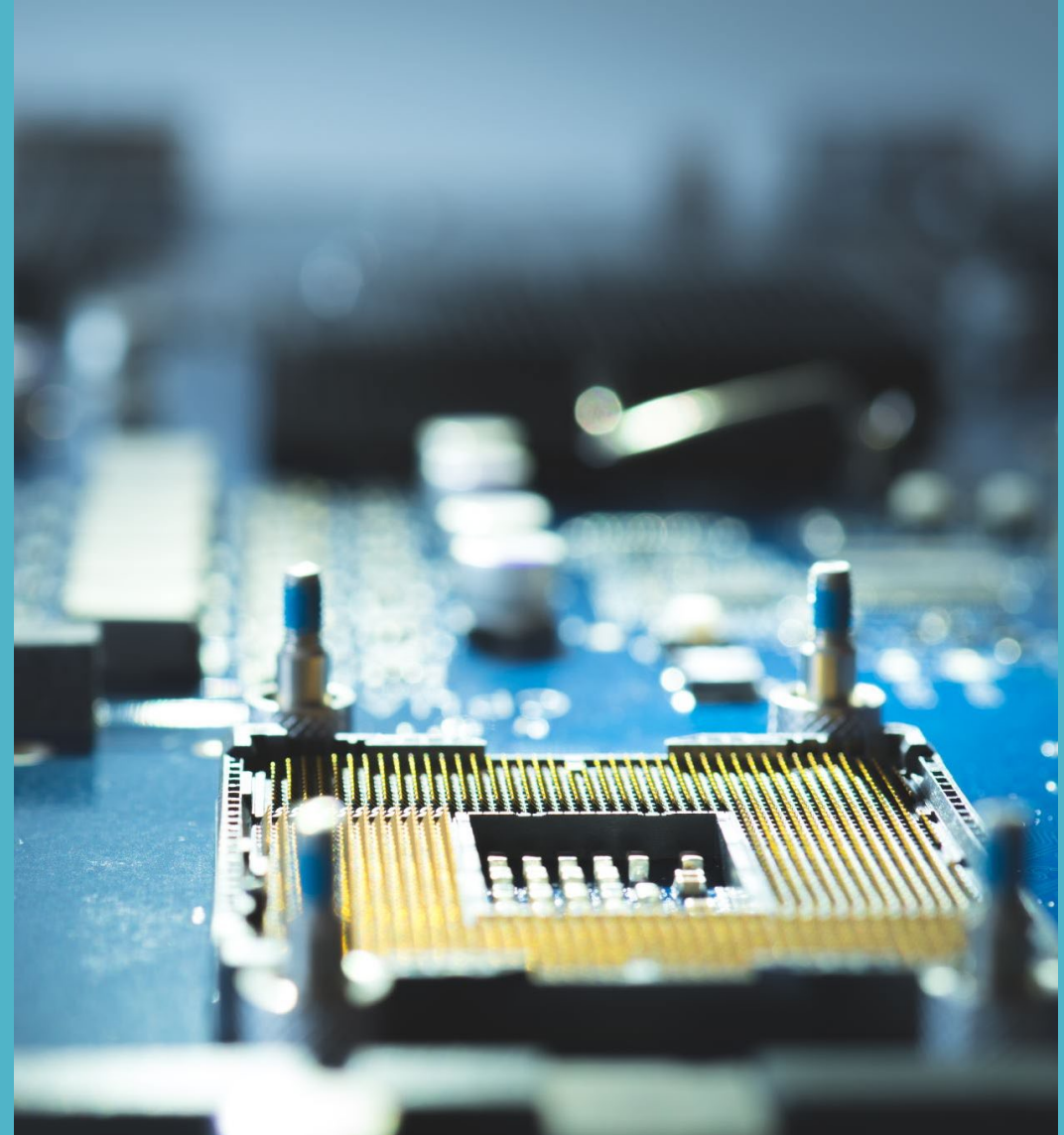


# Z-Transform

## Digital Control

Dr. Ahmad Al-Mahasneh



# In the previous lecture

- ❖ Sampling
- ❖ Quantization
- ❖ Z-transform

# Outline

1. Properties of z-transform
2. Inverse z-Transforms

**Table 6.1** | Some commonly used  $z$ -transforms

$f(kT)$	$F(z)$
$\delta(t)$	1
1	$\frac{z}{z-1}$
$kT$	$\frac{Tz}{(z-1)^2}$
$e^{-akT}$	$\frac{z}{z-e^{-aT}}$
$kT e^{-akT}$	$\frac{Tz e^{-aT}}{(z-e^{-aT})^2}$
$a^k$	$\frac{z}{z-a}$
$1 - e^{-akT}$	$\frac{z(1-e^{-aT})}{(z-1)(z-e^{-aT})}$
$\sin akT$	$\frac{z \sin aT}{z^2 - 2z \cos aT + 1}$
$\cos akT$	$\frac{z(z - \cos aT)}{z^2 - 2z \cos aT + 1}$

Laplace transform	Corresponding $z$ -transform
$\frac{1}{s}$	$\frac{z}{z-1}$
$\frac{1}{s^2}$	$\frac{Tz}{(z-1)^2}$
$\frac{1}{s^3}$	$\frac{T^2z(z+1)}{2(z-1)^3}$
$\frac{1}{s+a}$	$\frac{z}{z-e^{-aT}}$
$\frac{1}{(s+a)^2}$	$\frac{Tze^{-aT}}{(z-e^{-aT})^2}$
$\frac{a}{s(s+a)}$	$\frac{z(1-e^{-aT})}{(z-1)(z-e^{-aT})}$
$\frac{b-a}{(s+a)(s+b)}$	$\frac{z(e^{-aT}-e^{-bT})}{(z-e^{-aT})(z-e^{-bT})}$
$\frac{(b-a)s}{(s+a)(s+b)}$	$\frac{(b-a)z^2 - (be^{-aT} - ae^{-bT})z}{(z-e^{-aT})(z-e^{-bT})}$
$\frac{a}{s^2+a^2}$	$\frac{z \sin aT}{z^2 - 2z \cos aT + 1}$
$\frac{s}{s^2+a^2}$	$\frac{z^2 - z \cos aT}{z^2 - 2z \cos aT + 1}$
$\frac{s}{(s+a)^2}$	$\frac{z[z - e^{-aT}(1+aT)]}{(z-e^{-aT})^2}$

# Properties of Z-Transforms

Most of the properties of the  $z$ -transform are analogs of those of the Laplace transforms. Important  $z$ -transform properties are discussed in this section.

## 1. Linearity property

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$  and the  $z$ -transform of  $g(nT)$  is  $G(z)$ . Then

$$Z[f(nT) \pm g(nT)] = Z[f(nT)] \pm Z[g(nT)] = F(z) \pm G(z) \quad (6.20)$$

and for any scalar  $a$

$$Z[af(nT)] = aZ[f(nT)] = aF(z) \quad (6.21)$$

# Properties of Z-Transforms

## 2. Left-shifting property

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$  and let  $y(nT) = f(nT + mT)$ . Then

$$Y(z) = z^m F(z) - \sum_{i=0}^{m-1} f(iT)z^{m-i}. \quad (6.22)$$

If the initial conditions are all zero, i.e.  $f(iT) = 0, i = 0, 1, 2, \dots, m - 1$ , then,

$$Z[f(nT + mT)] = z^m F(z). \quad (6.23)$$

## 3. Right-shifting property

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$  and let  $y(nT) = f(nT - mT)$ . Then

$$Y(z) = z^{-m} F(z) + \sum_{i=0}^{m-1} f(iT - mT)z^{-i}. \quad (6.24)$$

If  $f(nT) = 0$  for  $k < 0$ , then the theorem simplifies to

$$Z[f(nT - mT)] = z^{-m} F(z). \quad (6.25)$$

# Properties of Z-Transforms

## 4. Attenuation property

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$ . Then,

$$Z[e^{-anT} f(nT)] = F[ze^{aT}]. \quad (6.26)$$

This result states that if a function is multiplied by the exponential  $e^{-anT}$  then in the  $z$ -transform of this function  $z$  is replaced by  $ze^{aT}$ .

## 5. Initial value theorem

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$ . Then the initial value of the time response is given by

$$\lim_{n \rightarrow 0} f(nT) = \lim_{z \rightarrow \infty} F(z). \quad (6.27)$$



# Properties of Z-Transforms

## 6. Final value theorem

Suppose that the  $z$ -transform of  $f(nT)$  is  $F(z)$ . Then the final value of the time response is given by

$$\lim_{n \rightarrow \infty} f(nT) = \lim_{z \rightarrow 1} (1 - z^{-1})F(z). \quad (6.28)$$

Note that this theorem is valid if the poles of  $(1 - z^{-1})F(z)$  are inside the unit circle or at  $z = 1$ .

# Properties of Z-Transforms: Examples

## **Example 6.3**

The  $z$ -transform of a unit ramp function  $r(nT)$  is

$$R(z) = \frac{Tz}{(z-1)^2}.$$

Find the  $z$ -transform of the function  $5r(nT)$ .

## ***Solution***

Using the linearity property of  $z$ -transforms,

$$Z[5r(nT)] = 5R(z) = \frac{5Tz}{(z-1)^2}.$$

# Properties of Z-Transforms: Examples

## Example 6.4

The  $z$ -transform of trigonometric function  $r(nT) = \sin n\omega T$  is

$$R(z) = \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1}.$$

find the  $z$ -transform of the function  $y(nT) = e^{-2nT} \sin n\omega T$ .

### *Solution*

Using property 4 of the  $z$ -transforms,

$$Z[y(nT)] = Z[e^{-2nT} r(nT)] = R[ze^{2T}].$$

Thus,

$$Z[y(nT)] = \frac{ze^{2T} \sin \omega T}{(ze^{2T})^2 - 2ze^{2T} \cos \omega T + 1} = \frac{ze^{2T} \sin \omega T}{z^2 e^{4T} - 2ze^{2T} \cos \omega T + 1}$$

or, multiplying numerator and denominator by  $e^{-4T}$ ,

$$Z[y(nT)] = \frac{ze^{-2T} \sin \omega T}{z^2 - 2ze^{-2T} \cos \omega T + e^{-4T}}.$$

# Properties of Z-Transforms: Examples

## Example 6.5

Given the function

$$G(z) = \frac{0.792z}{(z-1)(z^2 - 0.416z + 0.208)},$$

find the final value of  $g(nT)$ .

### *Solution*

Using the final value theorem,

$$\begin{aligned}\lim_{n \rightarrow \infty} g(nT) &= \lim_{z \rightarrow 1} (1 - z^{-1}) \frac{0.792z}{(z-1)(z^2 - 0.416z + 0.208)} \\ &= \lim_{z \rightarrow 1} \frac{0.792}{z^2 - 0.416z + 0.208} \\ &= \frac{0.792}{1 - 0.416 + 0.208} = 1.\end{aligned}$$

# Inverse Z-transform

- The inverse  $z$ -transform is obtained in a similar way to the inverse Laplace transforms.
- Generally, the  $z$ -transforms are the ratios of polynomials in the complex variable  $z$ , with the numerator polynomial being of order no higher than the denominator.
- By finding the inverse  $z$ -transform we find the sequence associated with the given  $z$ -transform polynomial. As in the case of inverse Laplace transforms, we are interested in the output time response of a system.
- Therefore, we use an inverse transform to obtain  $y(t)$  from  $Y(z)$ .

# Inverse Z-transform

➤ There are several methods to find the inverse z-transform of a given function.

➤ The following methods will be described here:

1. Power series (long division)
2. Expanding  $Y(z)$  into partial fractions and using z-transform tables to find the inverse transforms.
3. Obtaining the inverse z-transform using an inversion integral.

# Inverse Z-transform

Given a  $z$ -transform function  $Y(z)$ , we can find the coefficients of the associated sequence  $y(nT)$  at the sampling instants by using the inverse  $z$ -transform. The time function  $y(t)$  is then determined as

$$y(t) = \sum_{n=0}^{\infty} y(nT)\delta(t - nT).$$

*Method 1: Power series.* This method involves dividing the denominator of  $Y(z)$  into the numerator such that a power series of the form

$$Y(z) = y_0 + y_1z^{-1} + y_2z^{-2} + y_3z^{-3} + \dots$$

is obtained. Notice that the values of  $y(n)$  are the coefficients in the power series.

# Inverse Z-transform

## **Example 6.6**

Find the inverse  $z$ -transform for the polynomial

$$Y(z) = \frac{z^2 + z}{z^2 - 3z + 4}.$$



# Inverse Z-transform

## *Solution*

Dividing the denominator into the numerator gives

$$\begin{array}{r} 1 + 4z^{-1} + 8z^{-2} + 8z^{-3} \\ z^2 - 3z + 4 \overline{) z^2 + z} \\ \underline{z^2 - 3z + 4} \phantom{000} \\ 4z - 4 \\ 4z - 12 + 16z^{-1} \\ \underline{8 - 16z^{-1}} \\ 8 - 24z^{-1} + 32z^{-2} \\ \underline{8z^{-1} - 32z^{-2}} \\ 8z^{-1} - 24z^{-2} + 32z^{-3} \\ \dots \end{array}$$

and the coefficients of the power series are

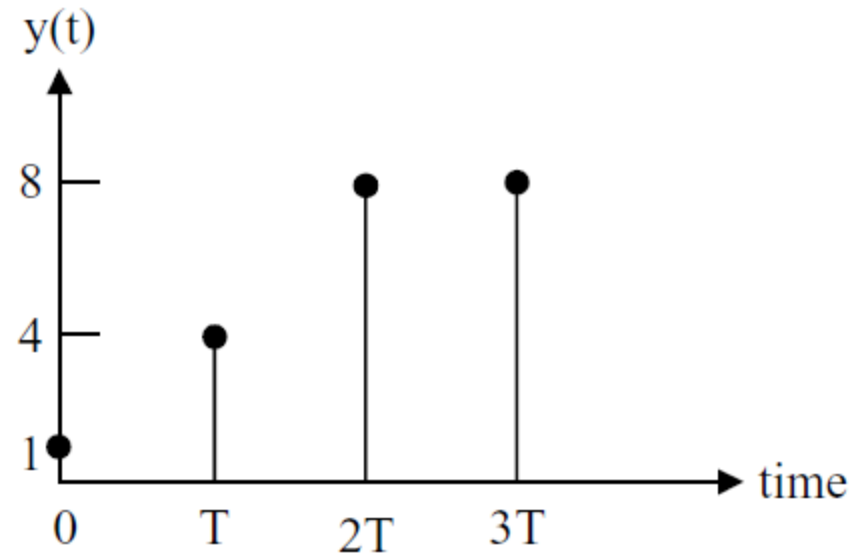
$$\begin{aligned} y(0) &= 1, \\ y(T) &= 4, \\ y(2T) &= 8, \\ y(3T) &= 8, \end{aligned}$$

# Inverse Z-transform

The required sequence is

$$y(t) = \delta(t) + 4\delta(t - T) + 8\delta(t - 2T) + 8\delta(t - 3T) + \dots$$

Figure 6.15 shows the first few samples of the time sequence  $y(nT)$ .



**Figure 6.15** First few samples of  $y(t)$

# Inverse Z-transform

## **Example 6.7**

Find the inverse  $z$ -transform for  $Y(z)$  given by the polynomial

$$Y(z) = \frac{z}{z^2 - 3z + 2}.$$

# Inverse Z-transform

## *Solution*

Dividing the denominator into the numerator gives

$$\begin{array}{r} z^{-1} + 3z^{-2} + 7z^{-3} + 15z^{-4} \\ z^2 - 3z + 2 \overline{) z} \\ \underline{z - 3 + 2z^{-1}} \\ 3 - 2z^{-1} \\ \underline{3 - 9z^{-1} + 6z^{-2}} \\ 7z^{-1} - 6z^{-2} \\ \underline{7z^{-1} - 21z^{-2} + 14z^{-3}} \\ 15z^{-2} - 14z^{-3} \\ \underline{15z^{-2} - 45z^{-3} + 30z^{-4}} \\ \dots \end{array}$$

and the coefficients of the power series are

$$y(0) = 0$$

$$y(T) = 1$$

$$y(2T) = 3$$

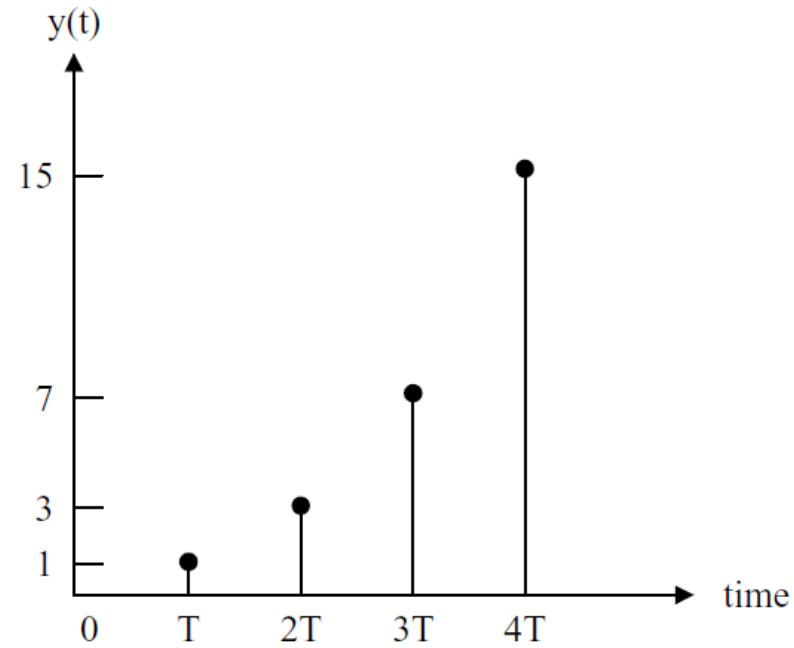
$$y(3T) = 7$$

$$y(4T) = 15$$

# Inverse Z-transform

The required sequence is thus

$$y(t) = \delta(t - T) + 3\delta(t - 2T) + 7\delta(t - 3T) + 15\delta(t - 4T) + \dots$$



**Figure 6.16** First few samples of  $y(t)$

# Inverse Z-transform

*Method 2: Partial fractions.* Similar to the inverse Laplace transform techniques, a partial fraction expansion of the function  $Y(z)$  can be found, and then tables of known  $z$ -transforms can be used to determine the inverse  $z$ -transform.

Looking at the  $z$ -transform tables, we see that there is usually a  $z$  term in the numerator. It is therefore more convenient to find the partial fractions of the function  $Y(z)/z$  and then multiply the partial fractions by  $z$  to obtain a  $z$  term in the numerator.

# Inverse Z-transform

## Example 6.8

Find the inverse  $z$ -transform of the function

$$Y(z) = \frac{z}{(z-1)(z-2)}$$

### *Solution*

The above expression can be written as

$$\frac{Y(z)}{z} = \frac{1}{(z-1)(z-2)} = \frac{A}{z-1} + \frac{B}{z-2}.$$

The values of  $A$  and  $B$  can be found by equating like powers in the numerator, i.e.

$$A(z-2) + B(z-1) \equiv 1.$$

We find  $A = -1$ ,  $B = 1$ , giving

$$\frac{Y(z)}{z} = \frac{-1}{z-1} + \frac{1}{z-2}$$

or

$$Y(z) = \frac{-z}{z-1} + \frac{z}{z-2}$$

# Inverse Z-transform

From the z-transform tables we find that

$$y(nT) = -1 + 2^n$$

and the coefficients of the power series are

$$\begin{aligned}y(0) &= 0, \\y(T) &= 1, \\y(2T) &= 3, \\y(3T) &= 7, \\y(4T) &= 15, \\&\dots\end{aligned}$$

so that the required sequence is

$$y(t) = \delta(t - T) + 3\delta(t - 2T) + 7\delta(t - 3T) + 15\delta(t - 4T) + \dots$$



# Inverse Z-transform

## **Example 6.9**

Find the inverse  $z$ -transform of the function

$$Y(z) = \frac{1}{(z-1)(z-2)}.$$

# Inverse Z-transform

## *Solution*

The above expression can be written as

$$\frac{Y(z)}{z} = \frac{1}{z(z-1)(z-2)} = \frac{A}{z} + \frac{B}{z-1} + \frac{C}{z-2}.$$

The values of  $A$ ,  $B$  and  $C$  can be found by equating like powers in the numerator, i.e.

$$A(z-1)(z-2) + Bz(z-2) + Cz(z-1) \equiv 1$$

or

$$A(z^2 - 3z + 2) + Bz^2 - 2Bz + Cz^2 - Cz \equiv 1,$$

giving

$$\begin{aligned} A + B + C &= 0, \\ -3A - 2B - C &= 0, \\ 2A &= 1. \end{aligned}$$

The values of the coefficients are found to be  $A = 0.5$ ,  $B = -1$  and  $C = 0.5$ . Thus,

$$\frac{Y(z)}{z} = \frac{1}{2z} - \frac{1}{z-1} + \frac{1}{2(z-2)}$$

# Inverse Z-transform

$$Y(z) = \frac{1}{2} - \frac{z}{z-1} + \frac{z}{2(z-2)}.$$

Using the inverse  $z$ -transform tables, we find

$$y(nT) = a - 1 + \frac{2^n}{2} = a - 1 + 2^{n-1}$$

where

$$a = \begin{cases} 1/2, & n = 0, \\ 0, & n \neq 0, \end{cases}$$

the coefficients of the power series are

$$y(0) = 0$$

$$y(T) = 0$$

$$y(2T) = 1$$

$$y(3T) = 3$$

$$y(4T) = 7$$

$$y(5T) = 15$$

...

# Inverse Z-transform

and the required sequence is

$$y(t) = \delta(t - 2T) + 3\delta(t - 3T) + 7\delta(t - 4T) + 15\delta(t - 5T) + \dots$$

# Inverse Z-transform

The process of finding inverse  $z$ -transforms is aided by considering what form is taken by the roots of  $Y(z)$ . It is useful to distinguish the case of distinct real roots and that of multiple order roots.

*Case I: Distinct real roots.* When  $Y(z)$  has distinct real roots in the form

$$Y(z) = \frac{N(z)}{(z - p_1)(z - p_2)(z - p_3) \dots (z - p_n)},$$

then the partial fraction expansion can be written as

$$Y(z) = \frac{A_1}{z - p_1} + \frac{A_2}{z - p_2} + \frac{A_3}{z - p_3} + \dots + \frac{A_n}{z - p_n}$$

and the coefficients  $A_i$  can easily be found as

$$A_i = (z - p_i) Y(z)|_{z=p_i} \quad \text{for } i = 1, 2, 3, \dots, n.$$

# Inverse Z-transform

## Example 6.10

Using the partial expansion method described above, find the inverse  $z$ -transform of

$$Y(z) = \frac{z}{(z-1)(z-2)}.$$

### *Solution*

Rewriting the function as

$$\frac{Y(z)}{z} = \frac{A}{z-1} + \frac{B}{z-2},$$

we find that

$$A = (z-1) \left. \frac{1}{(z-1)(z-2)} \right|_{z=1} = -1,$$

$$B = (z-2) \left. \frac{1}{(z-1)(z-2)} \right|_{z=2} = 1.$$

Thus,

$$Y(z) = \frac{z}{z-1} + \frac{z}{z-2}$$

and the inverse  $z$ -transform is obtained from the tables as

$$y(nT) = -1 + 2^n,$$

# Inverse Z-transform

## Example 6.11

Using the partial expansion method described above, find the inverse  $z$ -transform of

$$Y(z) = \frac{z^2 + z}{(z - 0.5)(z - 0.8)(z - 1)}.$$

# Inverse Z-transform

## *Solution*

Rewriting the function as

$$\frac{Y(z)}{z} = \frac{A}{z - 0.5} + \frac{B}{z - 0.8} + \frac{C}{z - 1}$$

we find that

$$A = (z - 0.5) \left. \frac{z + 1}{(z - 0.5)(z - 0.8)(z - 1)} \right|_{z=0.5} = 10,$$

$$B = (z - 0.8) \left. \frac{z + 1}{(z - 0.5)(z - 0.8)(z - 1)} \right|_{z=0.8} = -30,$$

$$C = (z - 1) \left. \frac{z + 1}{(z - 0.5)(z - 0.8)(z - 1)} \right|_{z=1} = 20.$$

Thus,

$$Y(z) = \frac{10z}{z - 0.5} - \frac{30z}{z - 0.8} + \frac{20z}{z - 1}$$

The inverse transform is found from the tables as

$$y(nT) = 10(0.5)^n - 30(0.8)^n + 20$$



# Inverse Z-transform

The coefficients of the power series are

$$y(0) = 0$$

$$y(T) = 1$$

$$y(2T) = 3.3$$

$$y(3T) = 5.89$$

...

and the required sequence is

$$y(t) = \delta(t - T) + 3.3\delta(t - 2T) + 5.89\delta(t - 3T) + \dots$$

# Inverse Z-transform

*Case II: Multiple order roots.* When  $Y(z)$  has multiple order roots of the form

$$Y(z) = \frac{N(z)}{(z - p_1)(z - p_1)^2(z - p_1)^3 \dots (z - p_1)^r},$$

then the partial fraction expansion can be written as

$$Y(z) = \frac{\lambda_1}{z - p_1} + \frac{\lambda_2}{(z - p_1)^2} + \frac{\lambda_3}{(z - p_1)^3} + \dots + \frac{\lambda_r}{(z - p_1)^r}$$

and the coefficients  $\lambda_i$  can easily be found as

$$\lambda_{r-k} = \frac{1}{k!} \left. \frac{d^k}{dz^k} [(z - p_i)^r (X(z)/z)] \right|_{z=p_i}. \quad (6.29)$$

# Inverse Z-transform

## Example 6.12

Using (6.29), find the inverse  $z$ -transform of

$$Y(z) = \frac{z^2 + 3z - 2}{(z + 5)(z - 0.8)(z - 2)^2}.$$

### *Solution*

Rewriting the function as

$$\frac{Y(z)}{z} = \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)(z - 2)^2} = \frac{A}{z} + \frac{B}{z + 5} + \frac{C}{z - 0.8} + \frac{D}{(z - 2)} + \frac{E}{(z - 2)^2}$$

we obtain

$$A = z \left. \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)(z - 2)^2} \right|_{z=0} = \frac{-2}{5 \times (-0.8) \times 4} = 0.125,$$

$$B = (z + 5) \left. \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)(z - 2)^2} \right|_{z=-5} = \frac{8}{-5 \times (-5.8) \times 49} = 0.0056,$$

$$C = (z - 0.8) \left. \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)(z - 2)^2} \right|_{z=0.8} = \frac{1.04}{0.8 \times 5.8 \times 1.14} = 0.16,$$

# Inverse Z-transform

$$E = (z - 2)^2 \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)(z - 2)^2} \Big|_{z=2} = \frac{8}{2 \times 7 \times 1.2} = 0.48,$$

$$\begin{aligned} D &= \frac{d}{dz} \left[ \frac{z^2 + 3z - 2}{z(z + 5)(z - 0.8)} \right] \Big|_{z=2} \\ &= \frac{[z(z + 5)(z - 0.8)(2z + 3) - (z^2 + 3z - 2)(3z^2 + 8.4z - 4)]}{(z^3 + 4.2z^2 - 4z)^2} \Big|_{z=2} = -0.29. \end{aligned}$$

We can now write  $Y(z)$  as

$$Y(z) = 0.125 + \frac{0.0056z}{z + 5} + \frac{0.016z}{z - 0.8} - \frac{0.29z}{(z - 2)} + \frac{0.48z}{(z - 2)^2}$$

The inverse transform is found from the tables as

$$y(nT) = 0.125a + 0.0056(-5)^n + 0.016(0.8)^n - 0.29(2)^n + 0.24n(2)^n,$$

where

$$a = \begin{cases} 1, & n = 0, \\ 0, & n \neq 0. \end{cases}$$

End

Thanks